

# Graph Coloring Facets from a Constraint Programming Formulation

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# Motivation

- **0-1** variables often encode choices that can be represented with **finite domain** variables.
  - $x_i =$  finite domain variable
    - Job assigned to worker  $i$
    - Start time of job  $i$
    - City visited after city  $i$
    - Number of packages on truck  $i$
  - $y_{ij} =$  corresponding 0-1 variable
    - $y_{ij} = 1$  if  $x_i = j$

# Motivation

- A **constraint programming** formulation often uses **finite-domain** variables.
  - If the variables are numeric, the problem has **polyhedral structure** very different from the 0-1 problem.
  - **Finite-domain cuts** can be mapped into the 0-1 model.
  - This may yield **stronger cuts** in the 0-1 model.

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  - **Finite-domain cuts** can be mapped into the 0-1 model.
  - This may yield **stronger cuts** in the 0-1 model.
- We apply this idea to **graph coloring**.
  - May apply to other problems with both 0-1 and CP formulations.

# Motivation

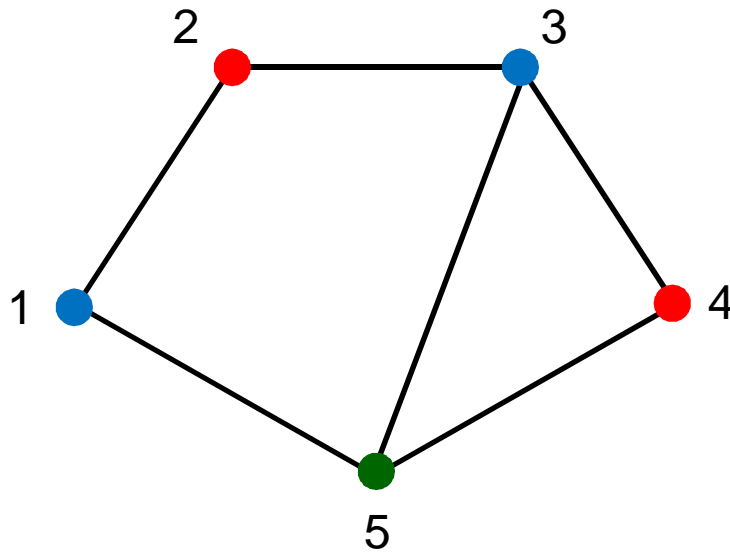
- We obtain two kinds of results:
  - If you find a structure (e.g., odd hole) that yields a known valid inequality in 0-1 space...
    - We will give you a stronger cut for **free**.
    - Use whatever separation algorithm you want.

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  - If you find a structure (e.g., odd hole) that yields a known valid inequality in 0-1 space...
    - We will give you a stronger cut for **free**.
    - Use whatever separation algorithm you want.
  - We identify **additional** structures that yield valid inequalities.
    - They are **stronger** than **known cuts**.
    - We have separation algorithms.

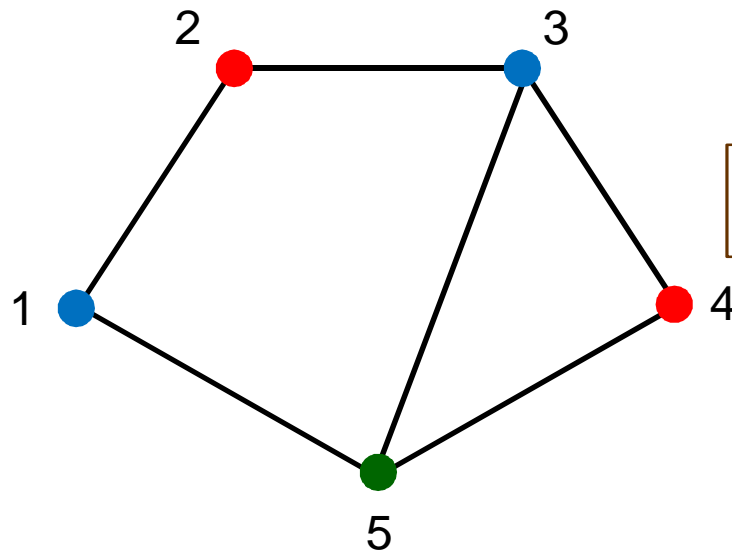
# Graph Coloring

- We focus on the **vertex coloring** problem.
  - Given a graph, assign colors to vertices so that no two adjacent vertices receive the same color.
  - Minimize the number of colors.



# Graph Coloring

- 0-1 model



= 1 if color  $j$  is used

$$\min \sum_j w_j$$

$$\sum_j y_{ij} = 1, \text{ all vertices } i$$

$$y_{1j} + y_{2j} \leq w_j, \text{ all colors } j$$

$$y_{1j} + y_{5j} \leq w_j, \text{ all colors } j$$

$$y_{2j} + y_{3j} \leq w_j, \text{ all colors } j$$

$$y_{3j} + y_{4j} + y_{5j} \leq w_j, \text{ all colors } j$$

$$y_{ij} \in \{0,1\}$$

= 1 if vertex  $i$   
receives color  $j$



# Graph Coloring

- General model:

$$\min \sum_j w_j$$

← = 1 if color  $j$  is used

$$\sum_j y_{ij} = 1, \text{ all vertices } i$$

$$\sum_{i \in V_k} y_{ij} \leq w_j, \text{ all colors } j, \text{ cliques } V_k \text{ that cover vertices}$$

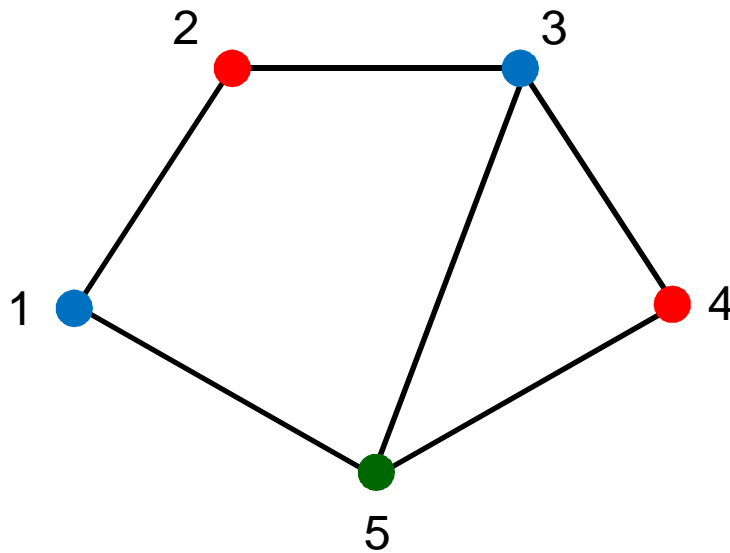
$$y_{ij} \in \{0,1\}$$

↑  
= 1 if vertex  $i$   
receives color  $j$

$O(n^2)$  variables  
 $O(n^3)$  constraints

# Alldiff Systems

- Use an **all-different** constraint for each clique.



min  $z$

$z \geq x_i$ , all vertices  $i$

alldiff( $x_1, x_2$ ), all colors  $j$

alldiff( $x_1, x_5$ ), all colors  $j$

alldiff( $x_2, x_3$ ), all colors  $j$

alldiff( $x_3, x_4, x_5$ ), all colors  $j$

$x_i \in \{1, \dots, 5\}$

= color assigned  
to vertex  $i$

# Alldiff Systems

- General model:

min  $z$

$z \geq x_i$ , all vertices  $i$

alldiff ( $x_i \mid i \in V_k$ ), all cliques  $V_k$

$x_i \in \{1, \dots, n\}$

↑  
= color assigned  
to vertex  $i$

$O(n)$  variables

$O(n^2)$  constraints

Objective reduces **symmetry**

# Alldiff Systems

- Applications:
  - Scheduling, timetabling.
    - Employee scheduling.
    - Course timetabling.
  - Latin squares.
    - Alldiff for each row, column.
    - Experimental design: orthogonal Latin squares.
    - Sudoku puzzles.
  - Graph coloring.
    - Many applications.

## Related Work

- Convex hull of single alldiff.
  - Hooker (2000), Williams and Yan (2001).
- Convex hull of 2 alldiffs.
  - Appa, Magos and Mourtos (2004)
- Convex hull of alldiff systems with inclusion property.
  - Appa, Magos and Mourtos (2011).
  - Same facets as individual alldiffs.
- Some facets of systems without inclusion property.
  - Magos and Mourtos (2011).

# Variable Mapping

- There is a linear mapping from  $x_i$  to  $y_{ij}$ :

$$x_i = \sum_j j y_{ij}$$

- Any valid linear inequality in  $x_i$ -space maps to a valid linear inequality in  $y_{ij}$ -space.
  - Just substitute above expression for  $x_i$ .
  - Convert any finite domain cut to a 0-1 cut.

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  - Just substitute above expression for  $x_i$ .
  - Convert any finite domain cut to a 0-1 cut.
- Objective function more likely to be linear in  $y$ -space.
  - For coloring, it is linear in both  $x$ -space and  $y$ -space.

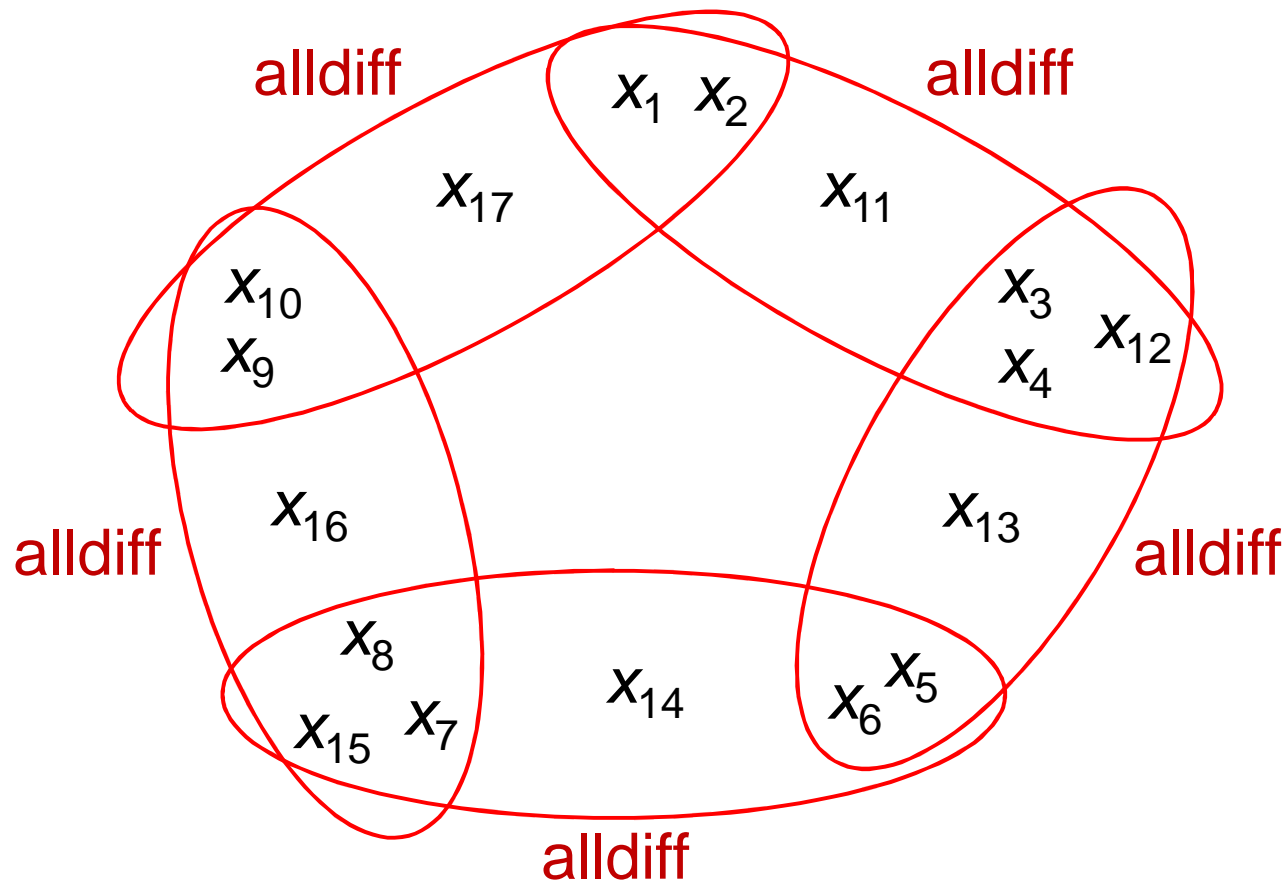
# Choice of Domain

- We will assume each  $x_i$  has domain  $\{0, \dots, n - 1\}$ .
  - To simplify exposition.
- Most results to follow can be generalized to an arbitrary numeric domain  $\{v_1, \dots, v_n\}$  with each  $v_i \geq 0$ .
  - Some results are valid for domain  $D = \{0, \delta, \dots, (n - 1)\delta\}$  with  $\delta > 0$ .



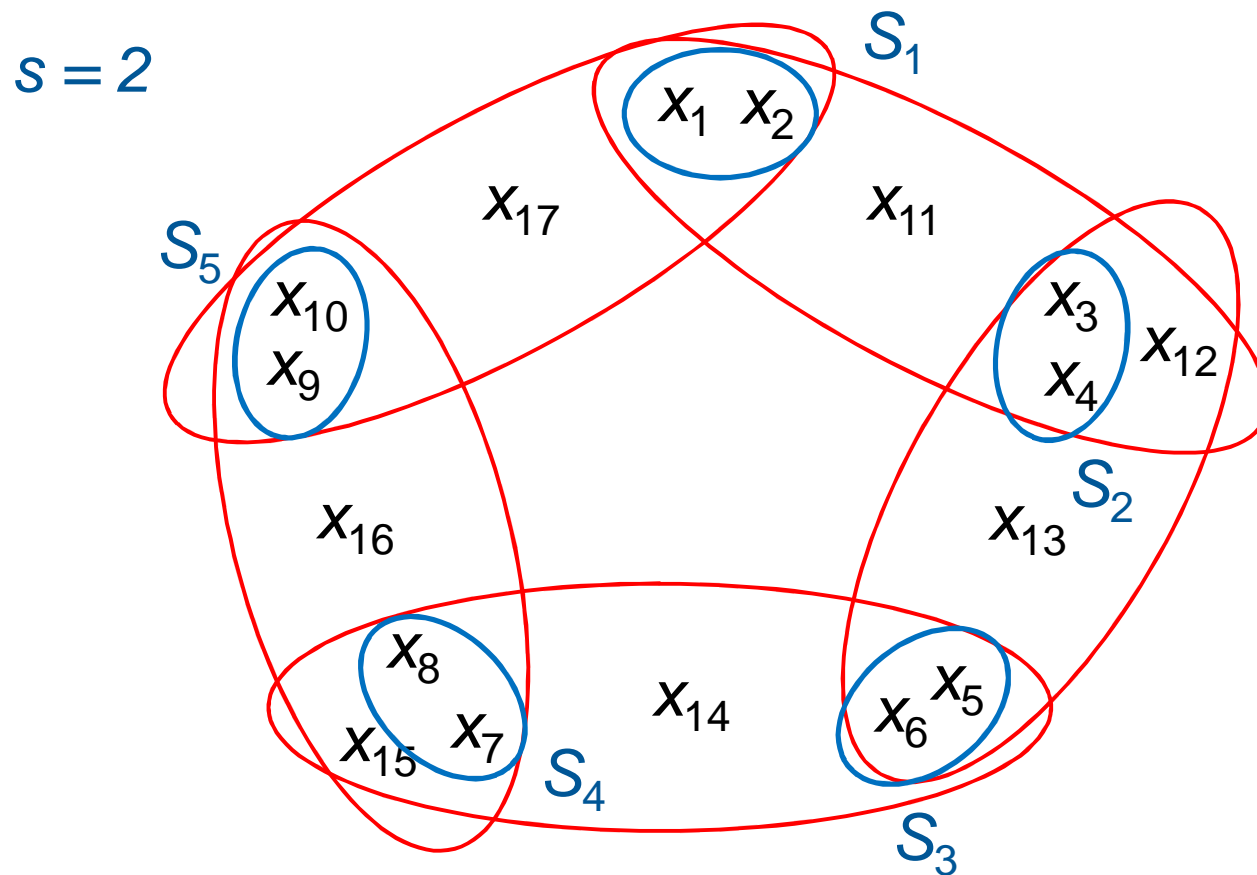
# Odd Cycles

- A  $q$ -cycle consists of  $q$  alldiff constraints that look like this:



# Odd Cycles

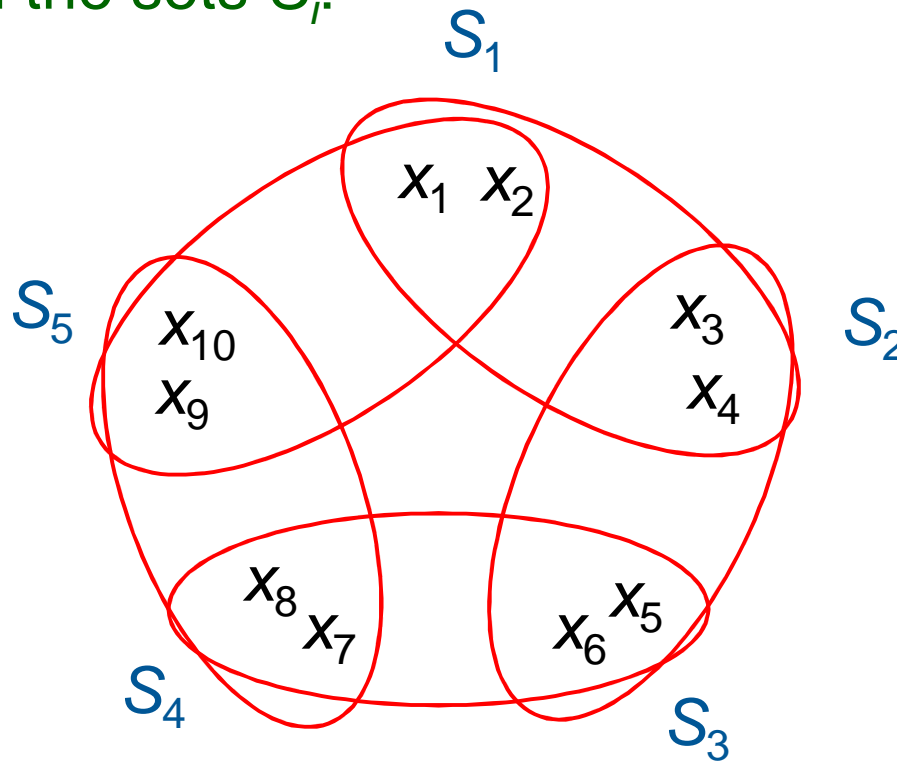
- Select any subset of  $s$  vertices in each overlap:



# Odd Cycles

- Focus on the sets  $S_i$ :

$$s = 2$$
$$q = 5$$



$sq = 10$  vertices

Each color can be assigned to at most  $(q - 1)/2 = 2$  vertices.

We need at least  $L = \left\lceil \frac{sq}{(q-1)/2} \right\rceil = 5$  colors

# Odd Cycles

- Focus on the sets  $S_i$ :

$$s = 2$$

$$q = 5 \quad S = \bigcup_k S_k$$

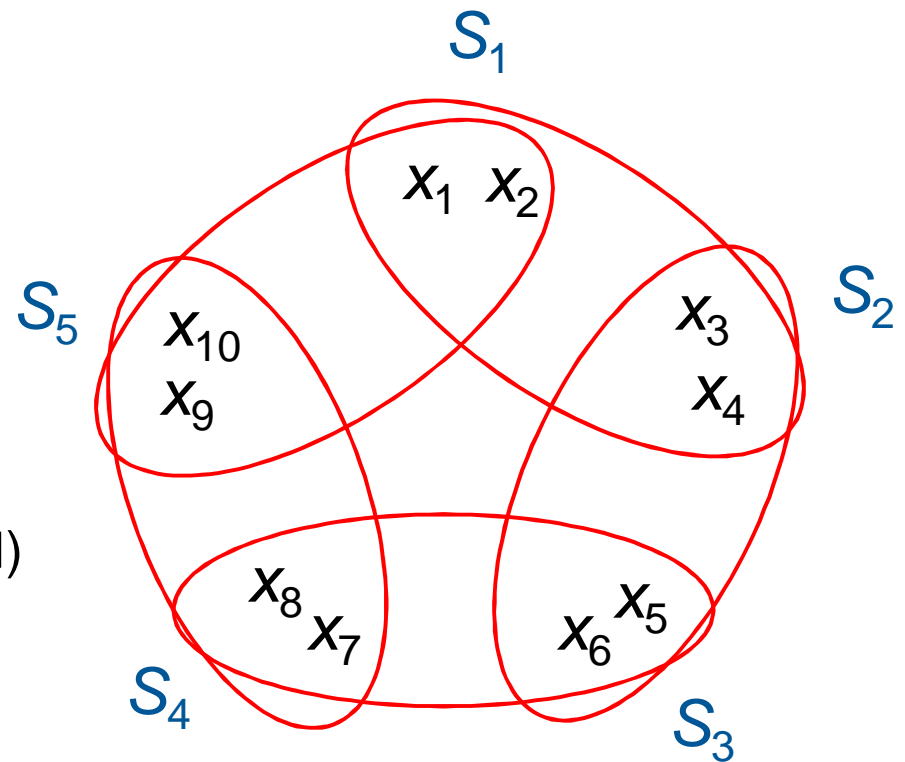
So

$$\sum_{i \in S} x_i \geq \frac{q-1}{2} \cdot 0 + \frac{q-1}{2} \cdot 1 + \dots$$

$$\dots + \frac{q-1}{2} (L-2) + \left( sq - \frac{q-1}{2} (L-1) \right) (L-1)$$

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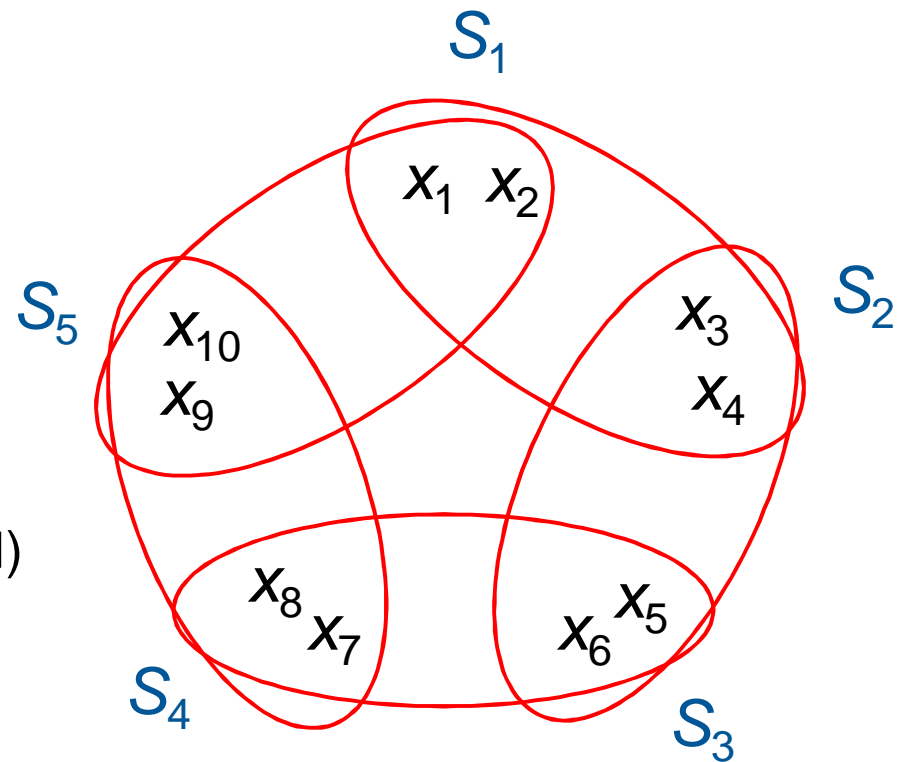
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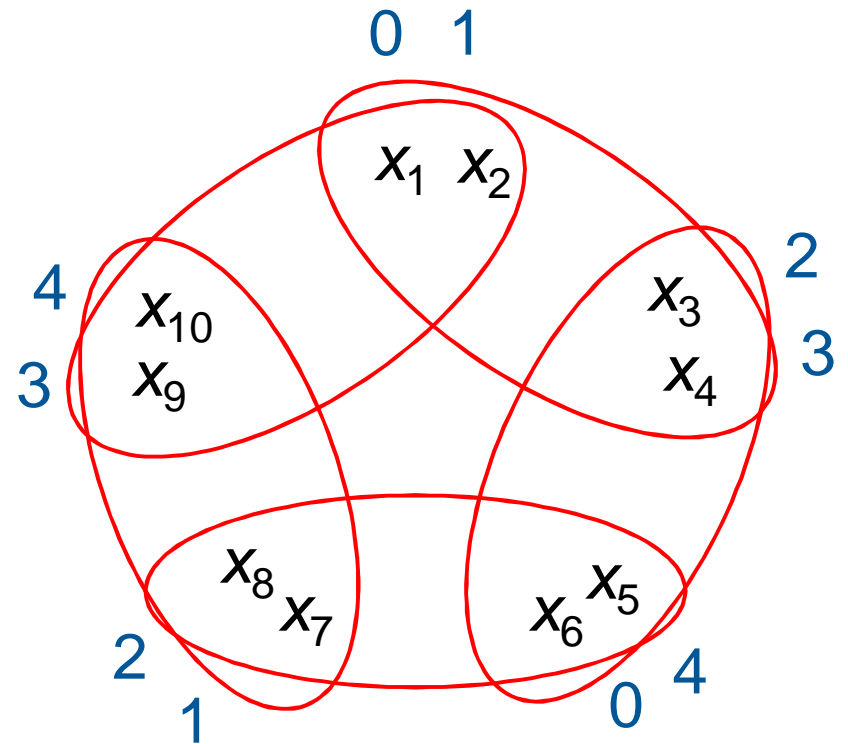
$$= \left( sq - \frac{q-1}{4} L \right) (L-1) = 20$$



# Odd Cycles

- So we have a valid inequality:

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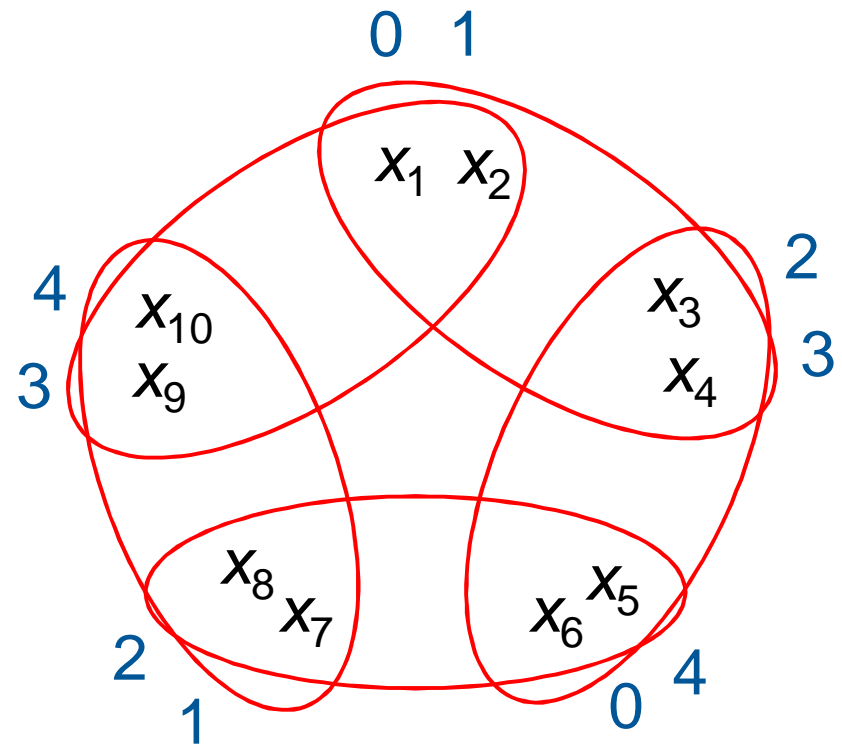


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- The inequality is **facet-defining** if  $q$  is odd.
  - and if the  $q$ -cycle is the subgraph induced by vertices in the cycle.



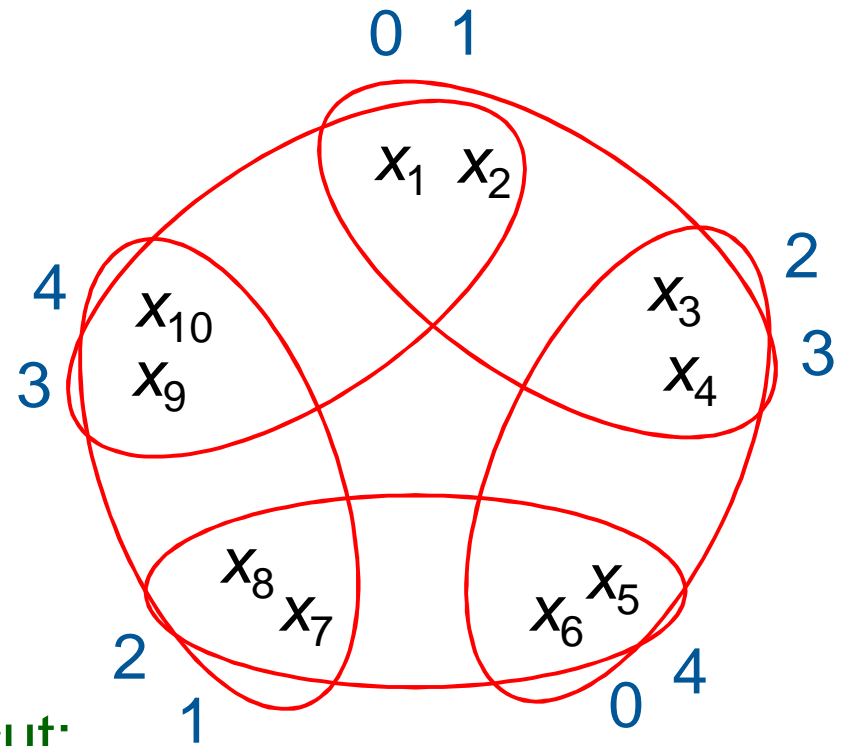
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- For  $s = 1$ , we have odd hole cut:

$$\sum_{i \in S} x_i \geq \frac{q+3}{2}$$





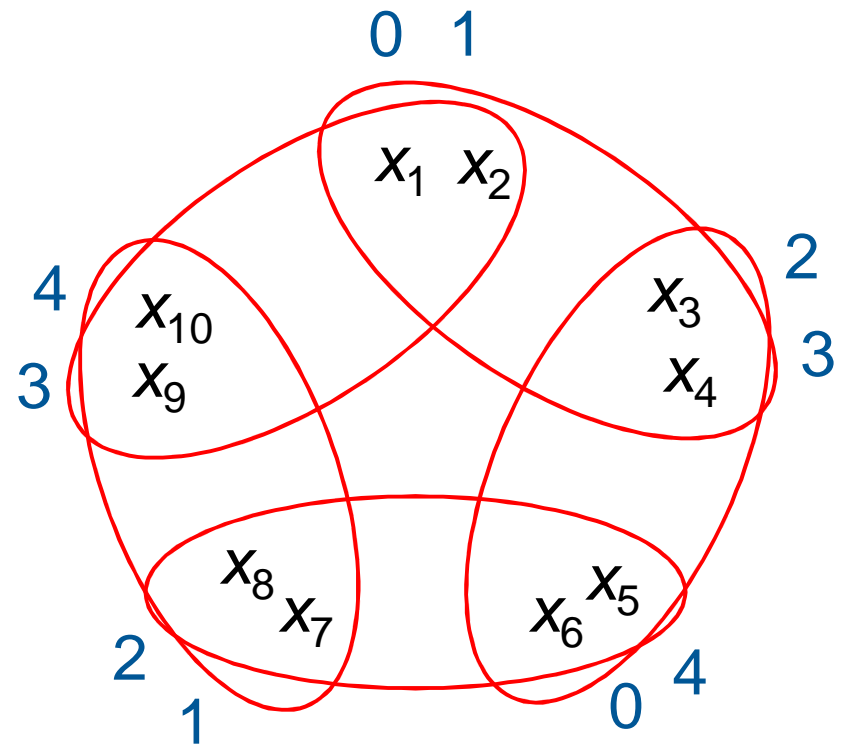
# Odd Cycles

- So we have a valid inequality:

$$\sum_{i \in S} x_i \geq \left( sq - \frac{q-1}{4} L \right) (L-1) = 20$$

- We can obtain a valid bound on number of colors  $z$  by substituting  $z - x_i$  for  $x_i$ :

$$\begin{aligned} z &\geq \frac{1}{qs} \sum_{i \in S} x_i + \left( 1 - \frac{q-1}{4qs} L \right) (L-1) \\ &= \frac{1}{10} \sum_{i \in S} x_i + 2 \end{aligned}$$



This is **facet defining** for domain  $D$ .

## z-cuts in general

- In fact, facet-defining **x**-cuts for a graph coloring problem always give rise to facet-defining **z**-cuts:
  - **Theorem:** if  $ax \geq b$  is facet defining for a coloring problem with domain  $D = \{0, \delta, 2\delta, \dots, (n - 1)\delta\}$  for  $\delta > 0$ , then  $aez \geq ax + b$  is also facet defining, where  $e = (1, \dots, 1)$ .

## Mapping into 0-1 Space

- The **x-cut**

$$\sum_{i \in S} x_i \geq \left( sq - \frac{q-1}{4} L \right) (L-1) = 20$$

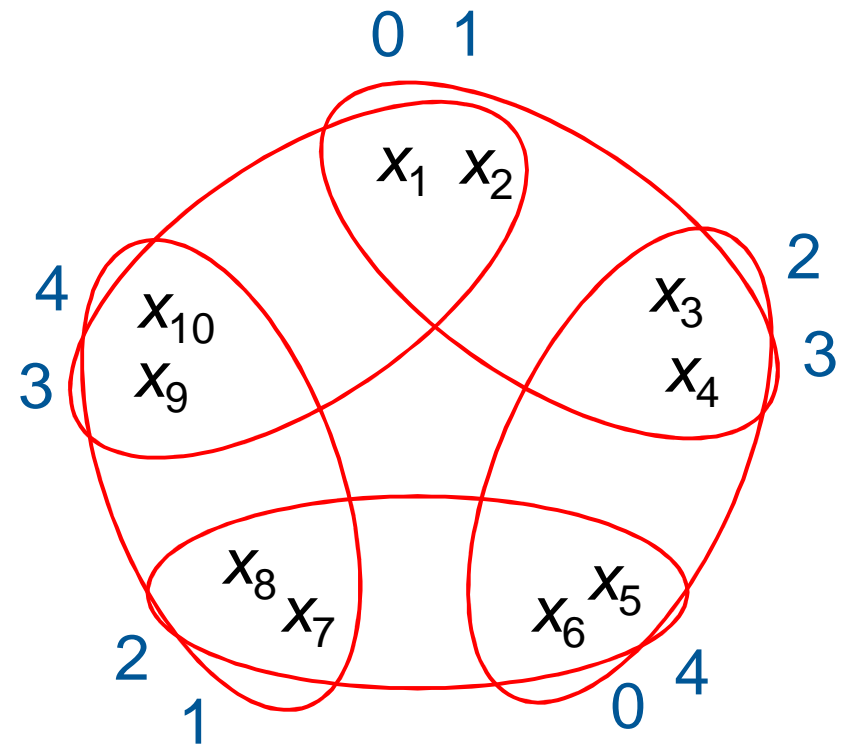
and the **z-cut**

$$z \geq \frac{1}{qs} \sum_{i \in S} x_i + \left( 1 - \frac{q-1}{4qs} L \right) (L-1)$$

map into a 0-1 cut

by replacing  $x_i$  with  $\sum_j j y_{ij}$

- How do they compare with classical odd hole cuts?

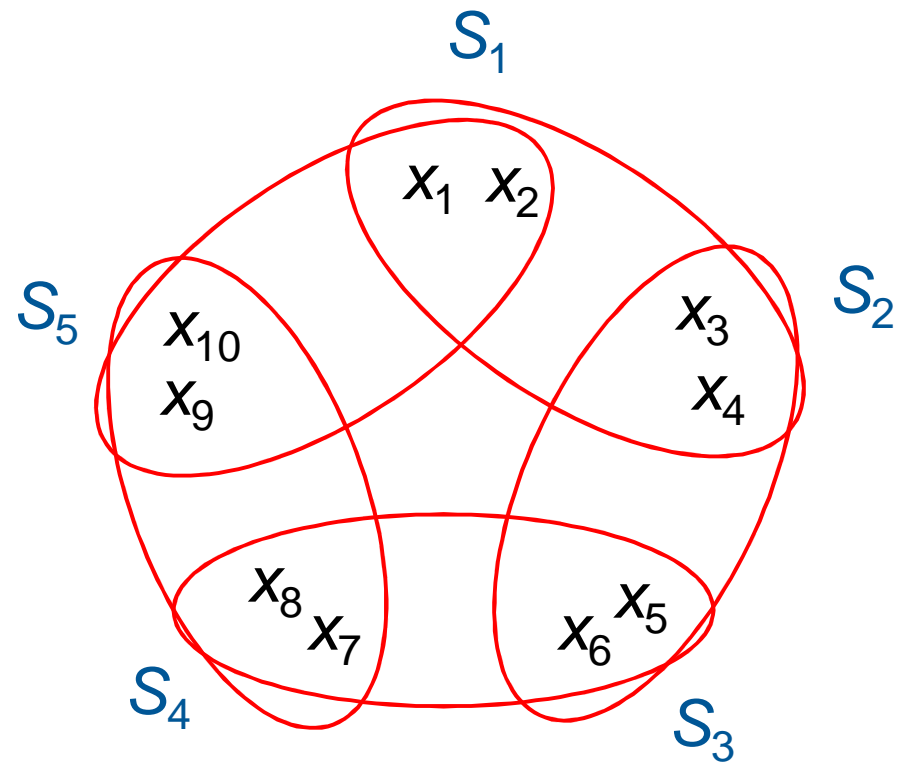


# Comparison with Odd Hole Cuts

- A  $q$ -cycle defines  $s^q = 32$  odd hole cuts for each color:

$$\sum_{i \in T} y_{ij} \leq \frac{q-1}{2} w_j, \text{ all } T, j$$

- where  $T$  selects one vertex from each  $S_k$



## Comparison with Odd Hole Cuts

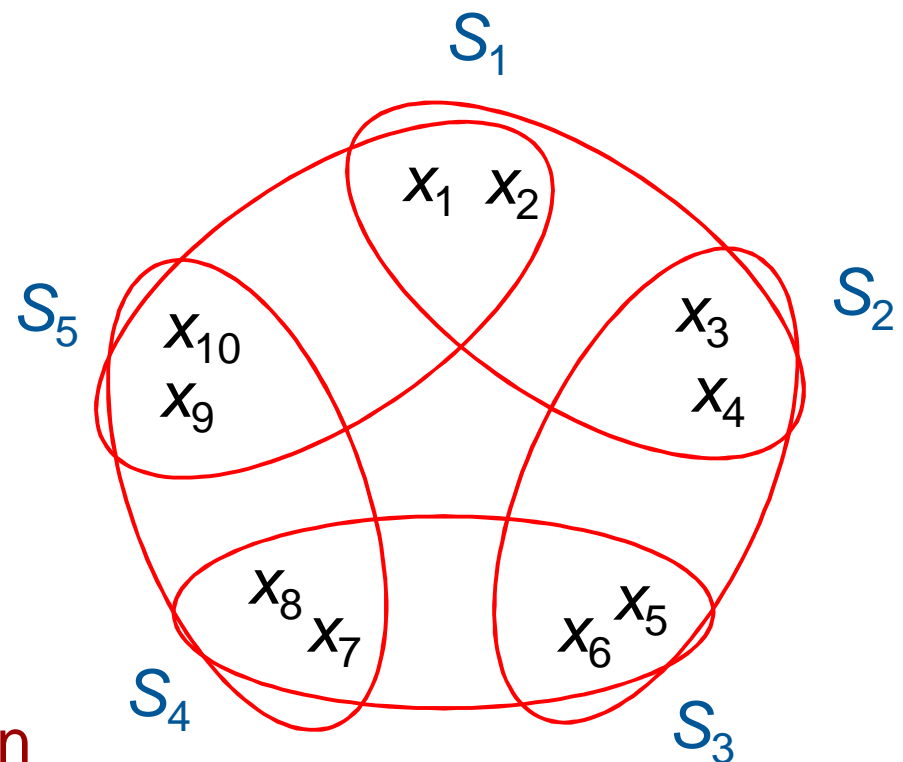
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- For  $s \geq 2$ , one  $x$ -cut is stronger than all of these odd hole cuts.

- For  $s = 1$ , the finite domain cut is redundant of odd cycle cuts and other 0-1 constraints.

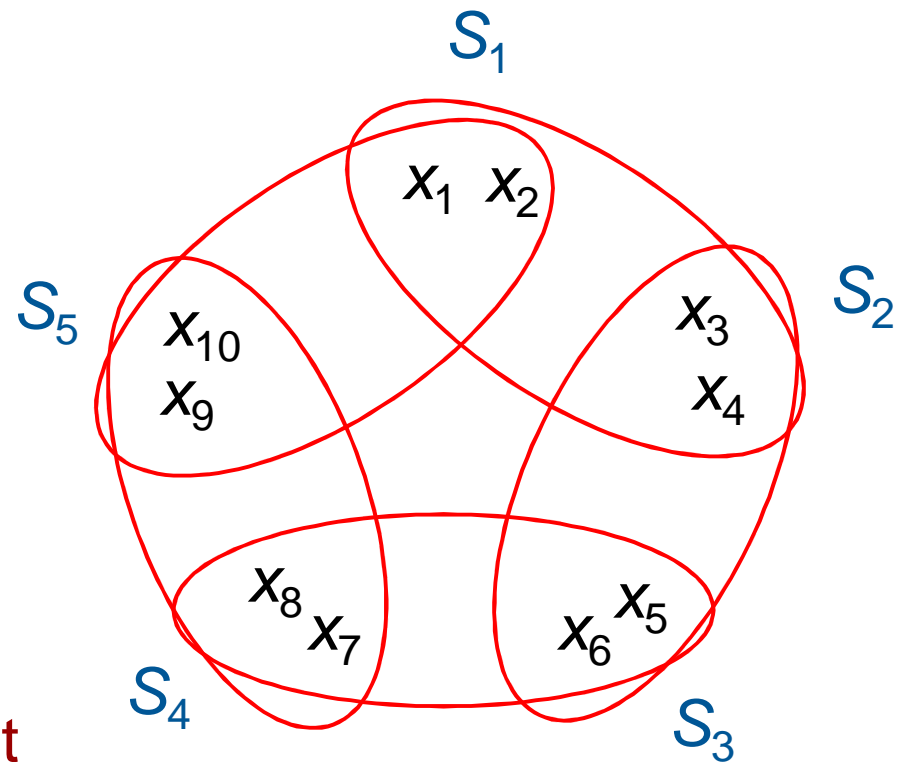


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- where  $T$  selects one vertex from each  $S_k$
- For  $s \geq 2$ , one  $\mathbf{x}$ -cut is stronger than all of these odd hole cuts.
  - Adding a  $\mathbf{z}$ -cut to the  $\mathbf{x}$ -cut tightens the bound further.



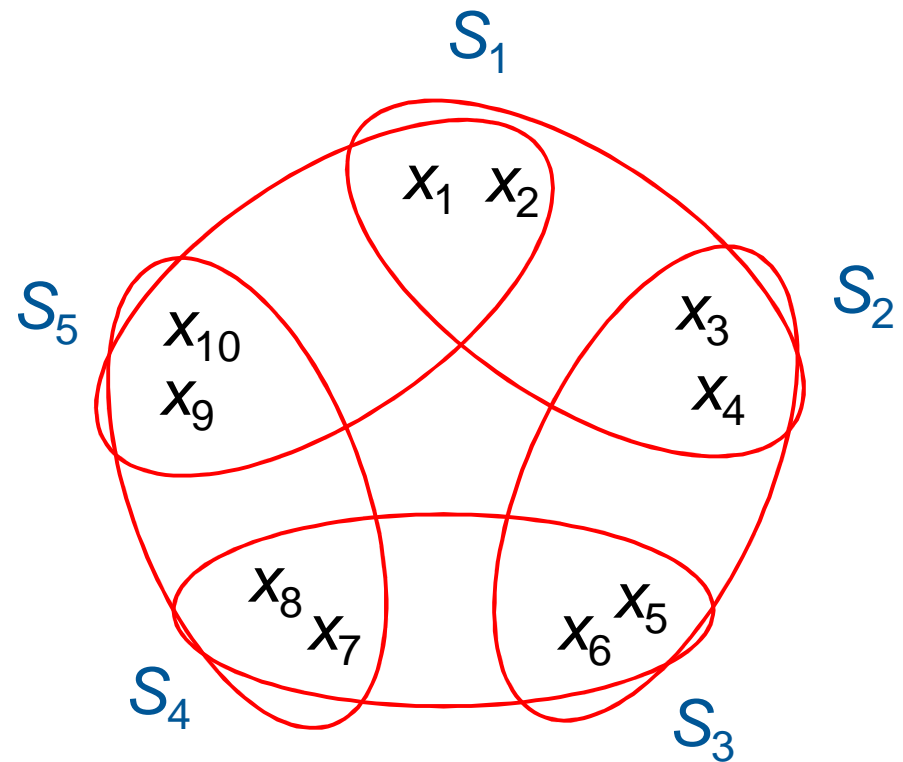
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– where  $T$  selects one vertex from each  $S_k$

- For **any**  $s$  (including  $s = 1$ ), one  $\mathbf{x}$ -cut and one  $\mathbf{z}$ -cut are stronger than all of these odd hole cuts.



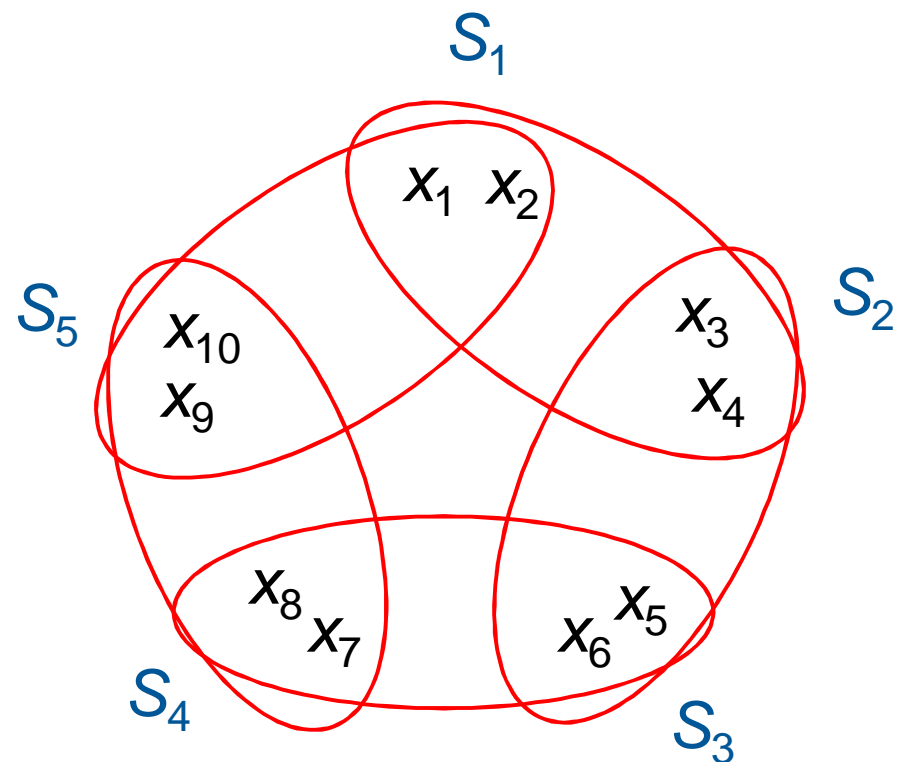
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- For **any**  $s$  (including  $s = 1$ ), one **x**-cut and one **z**-cut are stronger than all of these odd hole cuts.



- For any separating odd hole cut, replace it with **x**-cut and **z**-cut for  $s = 1$  to get a stronger cut.



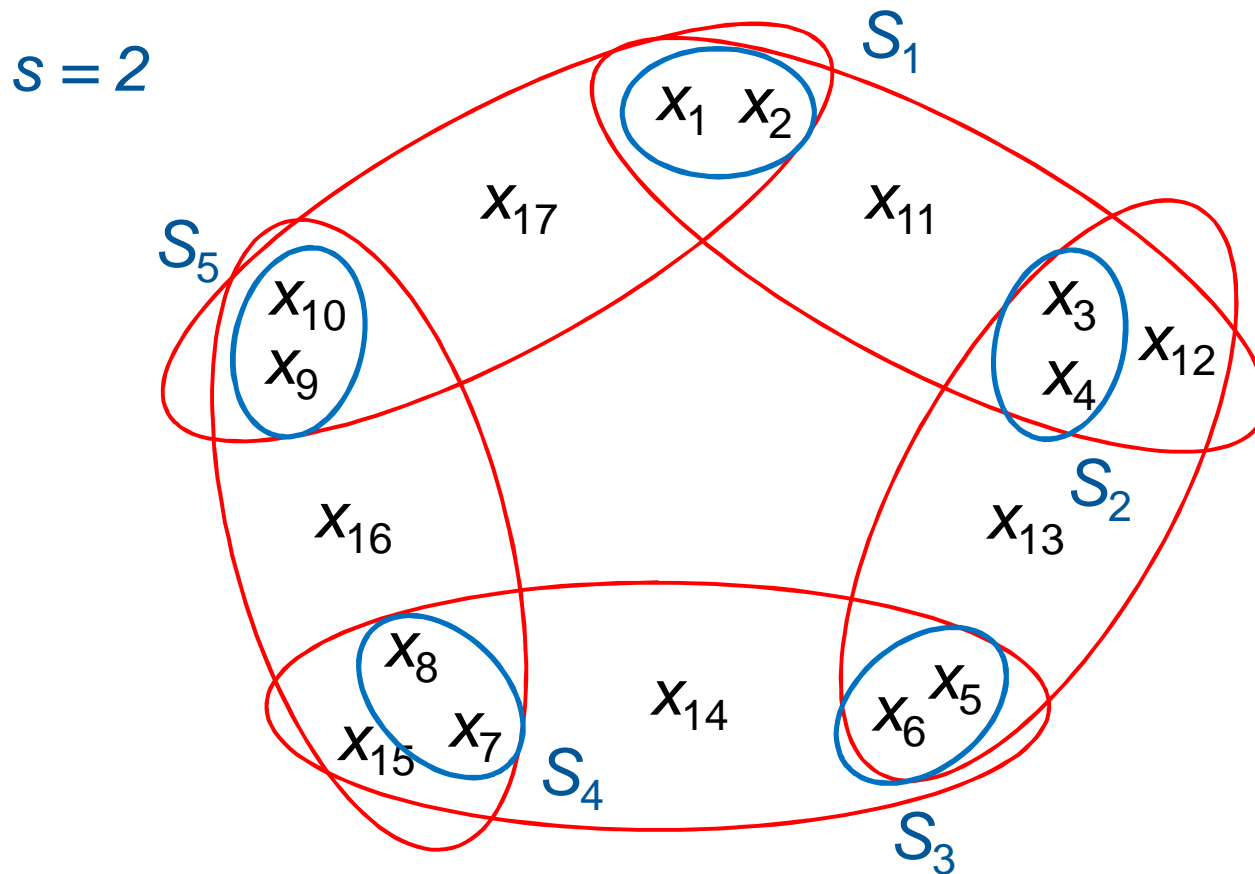
# Computed Bounds

Lower bound on number of colors in  
0-1 model of 5-cycle

<b>s =</b>	<b>1</b>	<b>2</b>	<b>3</b>
All odd hole cuts	0.8	1.5	2.500
<b>x</b> -cut only	0.8	2.0	3.267
<b>z</b> -cut only	1.3	3.5	5.767
<b>x</b> and <b>z</b> -cut only	1.6	4.0	6.533

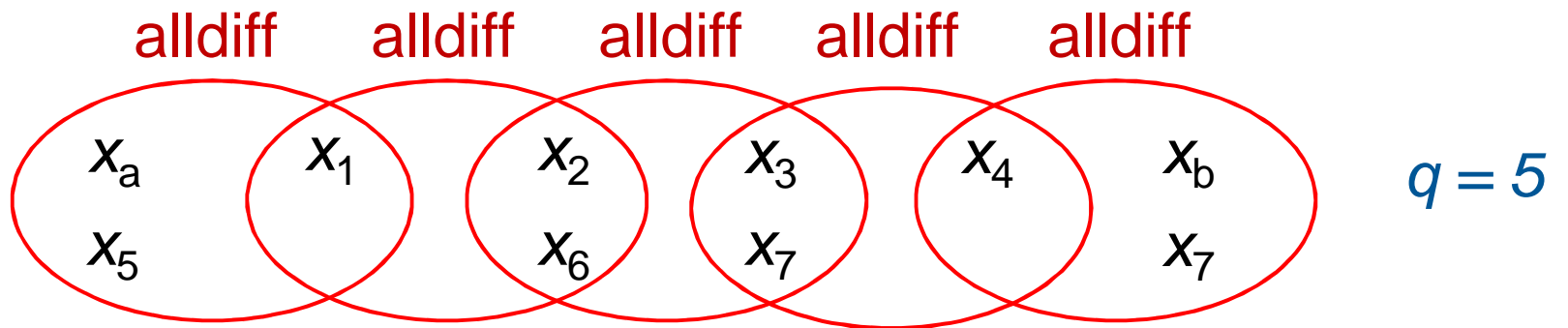
# Separation Heuristic

- Select subset of  $s$  vertices in each overlap with smallest values in current relaxation:



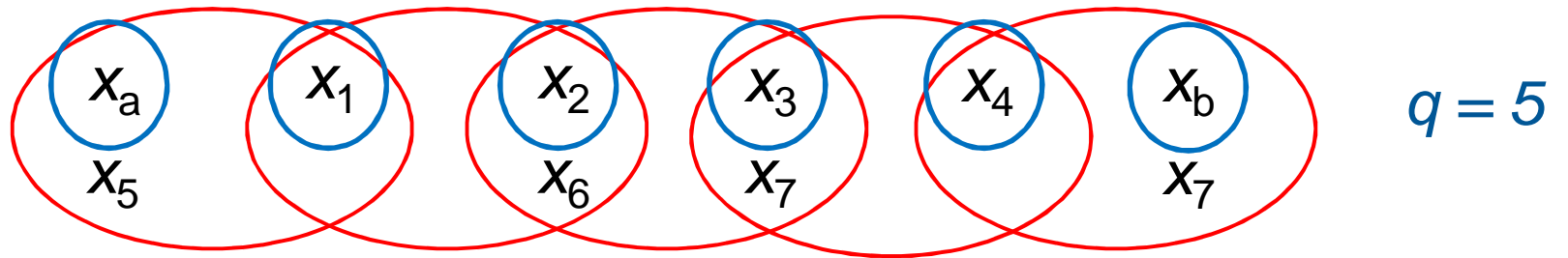
# Odd Paths

- A  $q$ -path looks like



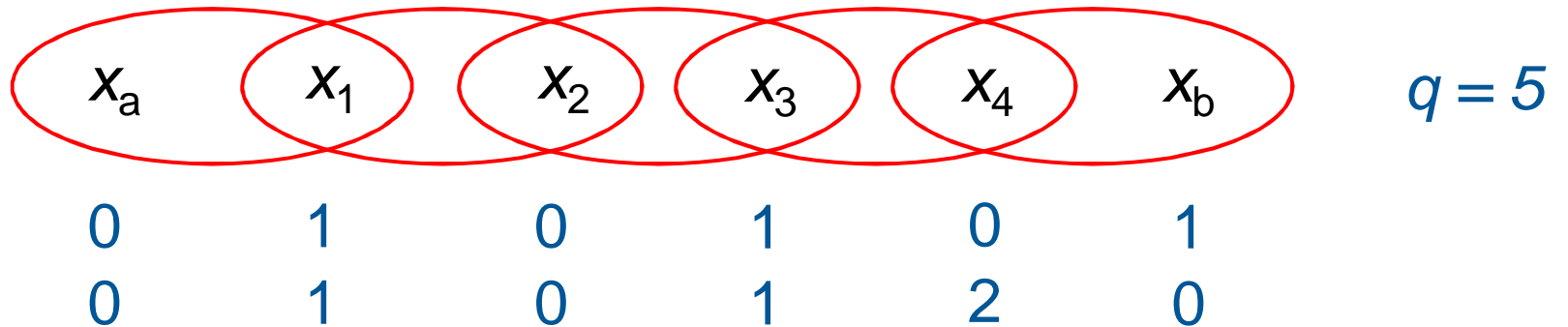
# Odd Paths

- Select  $q + 1$  variables:



# Odd Paths

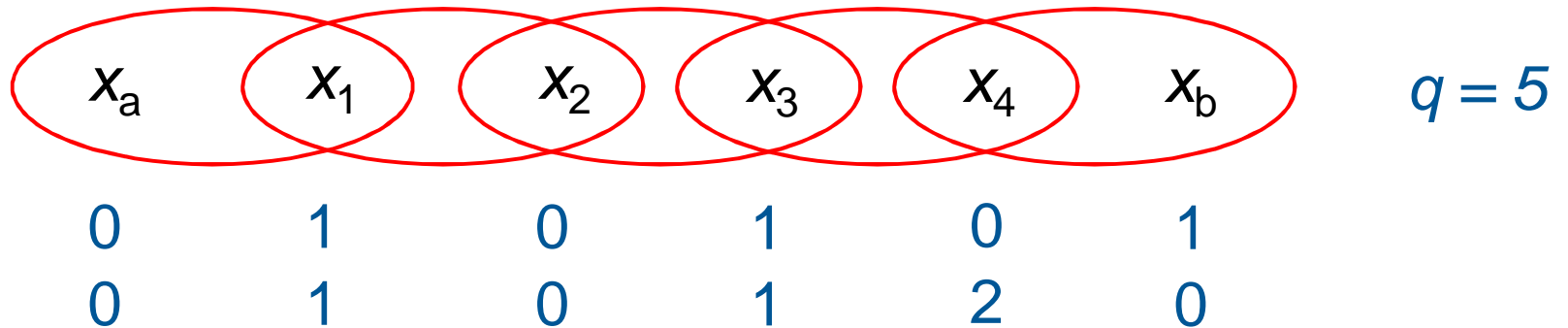
- This yields a valid inequality (**x**-cut)



$$2(x_a + x_b) + \sum_{i=1}^{q-1} x_i \geq \frac{q+3}{2} = 4$$

# Odd Paths

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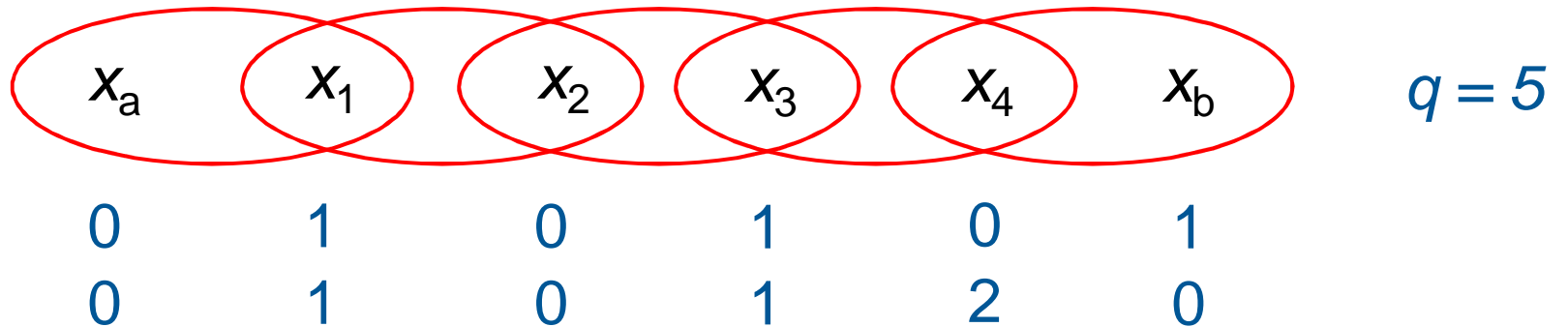


$$2(x_a + x_b) + \sum_{i=1}^{q-1} x_i \geq \frac{q+3}{2} = 4$$

- The inequality is **facet-defining** if  $q$  is odd.
  - and if the  $q$ -path is the subgraph induced by vertices in the cycle.

# Odd Paths

- We also have a **z**-cut



$$z \geq \frac{1}{q+3} \left( 2(x_a + x_b) + \sum_{i=1}^{q-1} x_i \right) + \frac{1}{2}$$

- This is also facet defining.



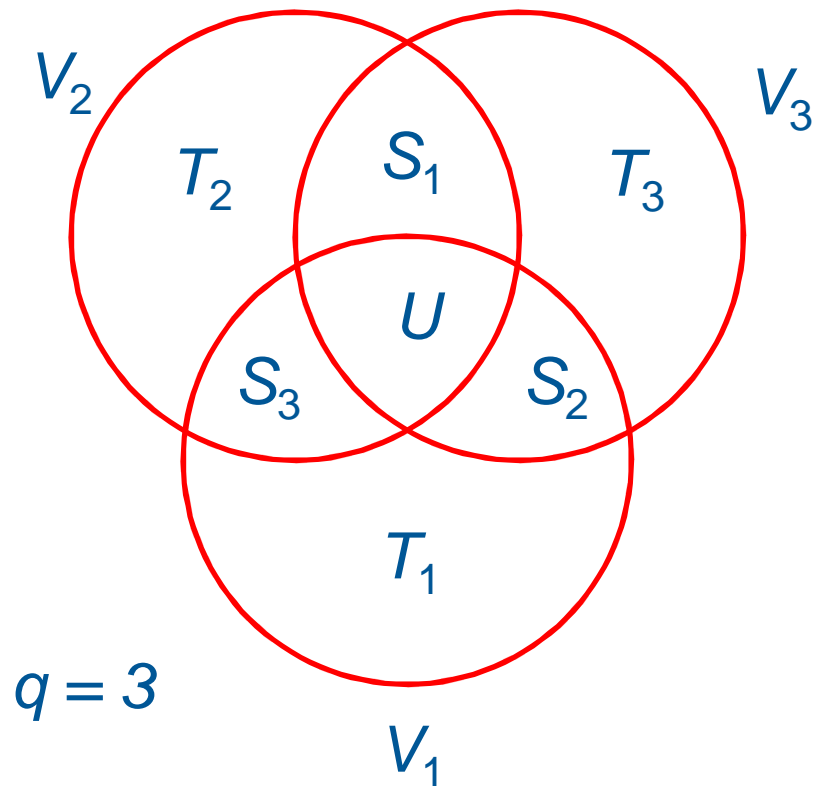


## Mapping into 0-1 Space

- When mapped into 0-1 space, the finite domain cuts are redundant of the 0-1 model.
  - Because the 0-1 model is already totally unimodular.
- However, the finite domain cuts provide a compact relaxation.
  - For each  $q$ -path, **replace**  $q$  clique constraints with one **x**-cut and one **y**-cut.
  - Gives the same bound in a problem consisting of one path.

# Clutters

- A  $q$ -clutter looks something like



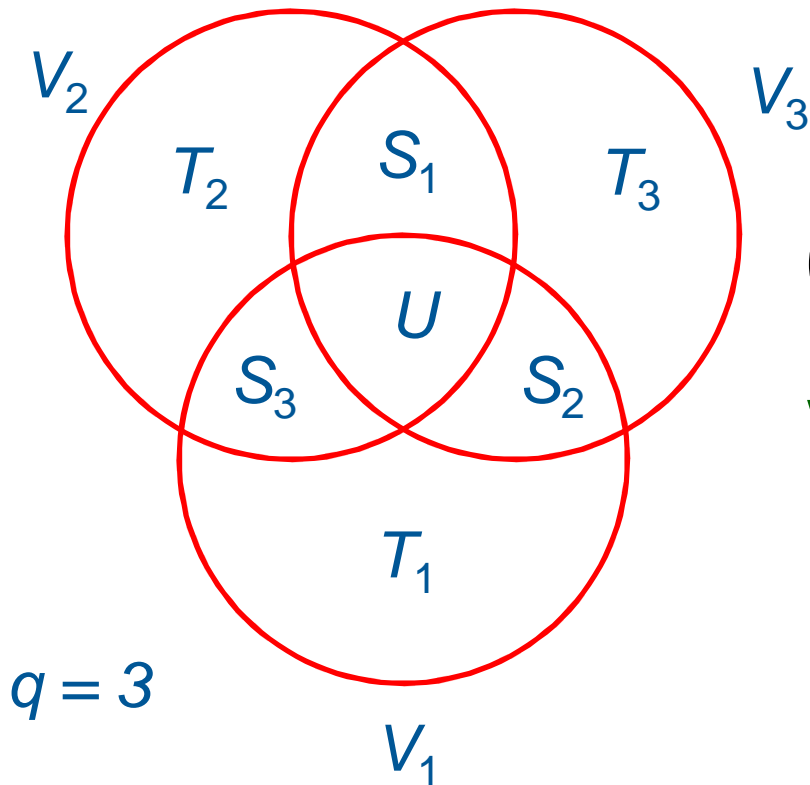
$$S_k = \bigcap_{l \neq k} V_l \setminus V_k$$

$$T_k = V_k \setminus \bigcup_{l \neq k} V_l$$

$$U = \bigcap_k V_k$$

# Clutters

- Facet-defining inequality. Let  $S = \bigcup_k S_k$   $T = \bigcup_k T_k$   $u = |U|$



A valid inequality is:

$$(qs + u) \sum_{i \in T} x_i + \frac{q(q-1)}{2} \sum_{i \in S \cup U} x_i \geq b$$

where

$$b = \frac{1}{2} q(q-1)(qs + u)(qs + u + 1)$$

Properties of 0-1 mapping?

## Another Interpretation

- Combine alternate formulations to obtain a better relaxation.
- Often done in constraint programming to obtain better propagation.
  - $x_i$  = job assigned to worker  $i$
  - $y_j$  = worker assigned to job  $j$
  - Write each constraint in one or both variable systems.
  - Add **channeling** constraints:

$$x_{y_j} = j, \quad \text{all } j$$

$$y_{x_i} = i, \quad \text{all } i$$

# Another Interpretation

- We are doing the same with relaxations.

## x relaxation

$$\min z$$

$$z \geq x_i, \text{ all } i$$

$$\sum_i x_i \geq \left( sq - \frac{q-1}{4} L \right) (L-1)$$

$$z \geq \frac{1}{qs} \sum_i x_i + \left( 1 - \frac{q-1}{4qs} L \right) (L-1)$$

$$x_i = \sum_j j y_{ij}$$



“channeling”  
constraint

## y relaxation

$$\min \sum_j w_j$$

$$\sum_j y_{ij} = 1, \text{ all } i$$

$$\sum_{i \in V_k} y_{ij} \leq w_j, \text{ all } j, V_k$$

$$0 \leq y_{ij} \leq 1$$

## Another Interpretation

- Neither relaxation alone provides a good bound.

5-cycle problem with  $s = 2$

	<b>Bound</b>
Odd hole cuts in $y$ -relaxation	1.5
Finite domain cuts in $x$ -relaxation	2.6
Combined models	4.0

# Future Work

- Map other known finite-domain cuts into 0-1 models. What happens?
  - Cardinality rules. Yan and Hooker (1999).
  - Circuit constraint (TSP). Genc-Kaya and Hooker (2010).
  - Cumulative constraint.
- Polyhedral analysis for other global constraints.
  - General cardinality, nvalues, sequence, regular.

# General Issues

- When do linked multiple relaxations provide better bounds than one relaxation?
- Can we say anything about the properties of different variable encodings?
- What are variables, and why do we use them?