

Logic, Optimization and Data Analytics

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Thesis

- **Logic and optimization have an underlying unity.**
 - Ideas from one area can solve problems in the other.
 - Ideas from both can be applied to **data analytics**.

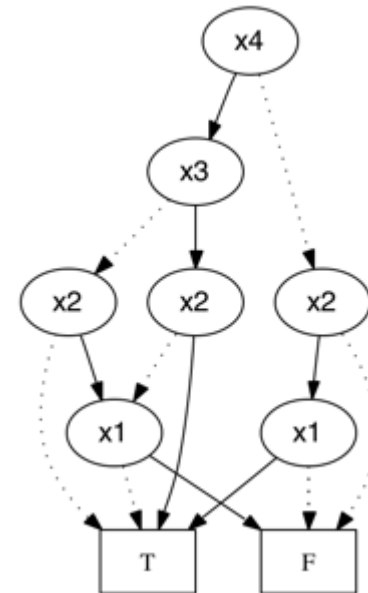
Research Programs

- Apply **logic-based methods** to **optimization**.
 - Decision diagrams.
 - Logic-based Benders decomposition
- Apply **optimization methods** to **logical inference** and **data analytics**.
 - Logic-based Benders decomposition.
 - Linear, integer, and nonlinear programming.

Decision Diagrams

- Graphical encoding of a boolean function
 - Historically used for circuit design & verification
 - Adapt to optimization and CP

Hadžić and JH (2006, 2007)



Decision Diagrams

- Collaborators...
 - Henrik Andersen
 - David Bergman*
 - André Ciré**
 - Tarik Hadžić
 - Samid Hoda
 - Willem-Jan van Hoeve
 - Barry O’Sullivan
 - Peter Tiedemann

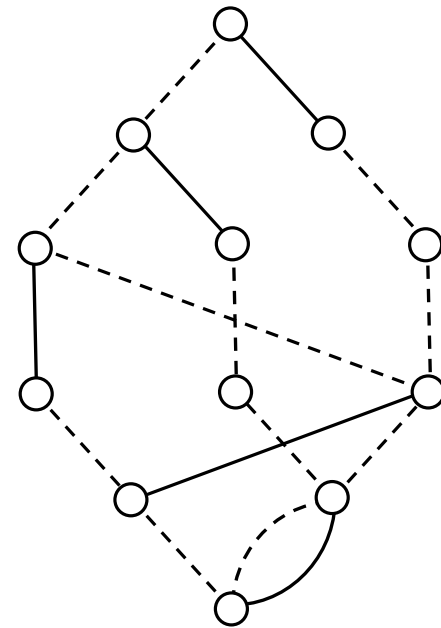
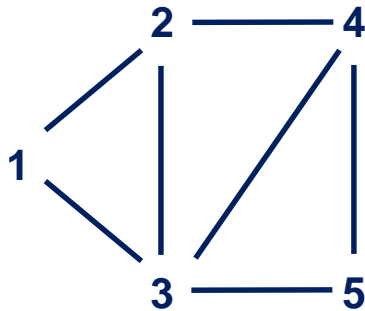
*2014 *Doctoral Thesis Award*, Association for CP

**2014 *Best Student Paper Award*, INFORMS Computing Society

Decision Diagrams

Example:
Stable set problem

Find max-weight subset
of nonadjacent vertices



x_1

x_2

x_3

x_4

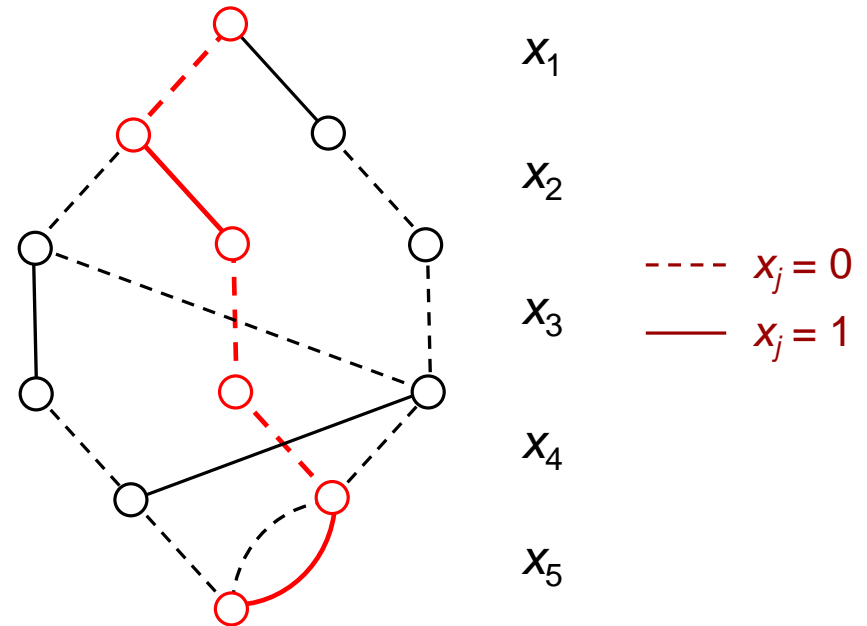
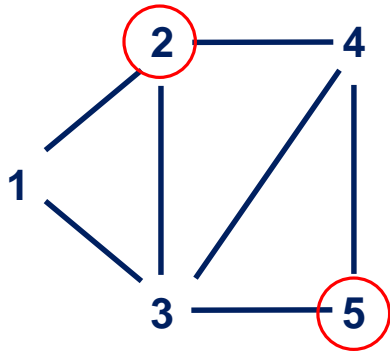
x_5

----- $x_j = 0$
——— $x_j = 1$

Decision Diagrams

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Stable set problem

Find max-weight subset
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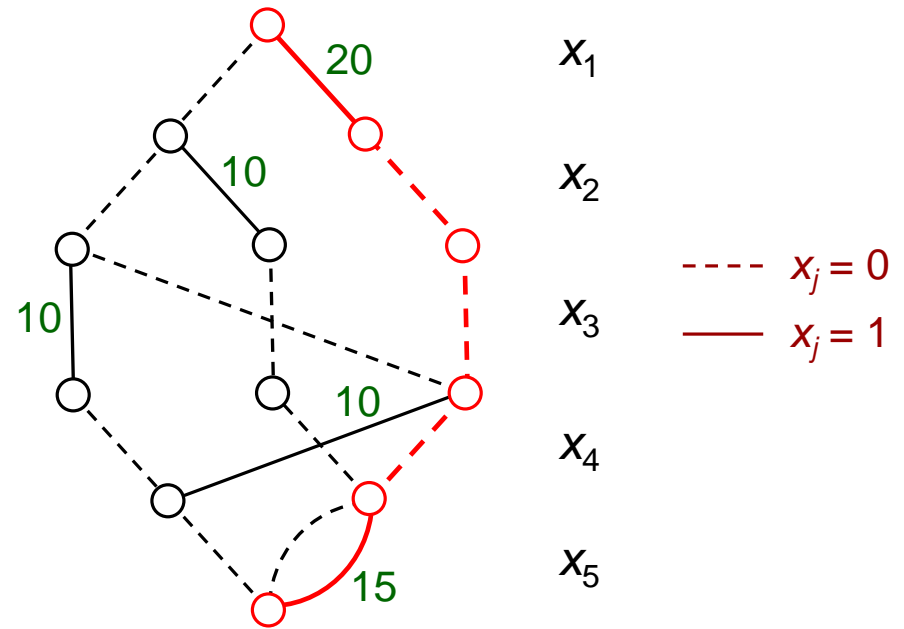
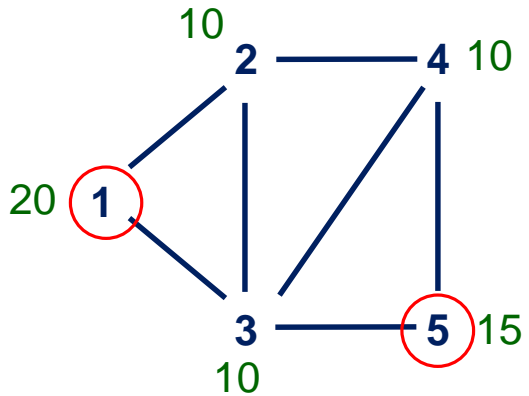


Each path corresponds to a feasible solution.

Decision Diagrams

Example:
Stable set problem

Find max-weight subset
of nonadjacent vertices



Longest path corresponds to an optimal solution.

Decision Diagrams

- Key idea: Use **relaxed** decision diagrams
 - Represent a superset of the feasible set
 - ... with a **limited-width** diagram.
 - First used to strengthen **propagation** in CP solvers.
 - Reduced 1 million node search trees to 1 node.

Andersen, Hadžić, JH, Tiedemann (2007)

Decision Diagrams

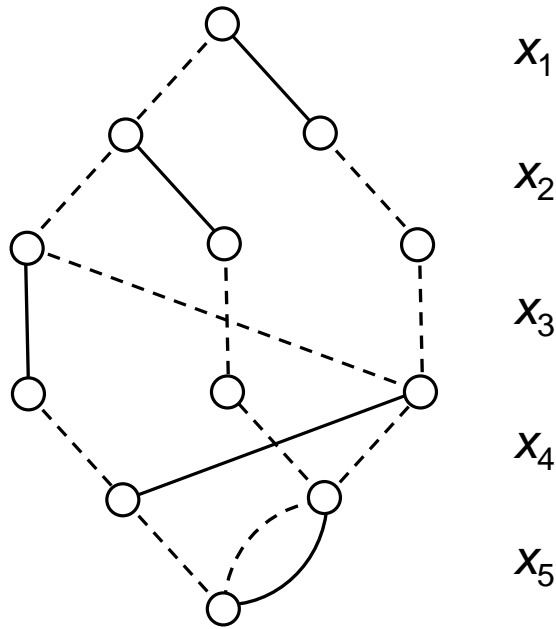
- Key idea: Use **relaxed** decision diagrams
 - Represent a superset of the feasible set
 - ... with a **limited-width** diagram.
 - First used to strengthen **propagation** in CP solvers.
 - Reduced 1 million node search trees to 1 node.

Andersen, Hadžić, JH, Tiedemann (2007)

- Shortest (longest) path in the decision diagram provides a **bound** on optimal value.
 - Leads to general-purpose **optimization** method.

Bergman, Ciré, van Hoeve, JH (2013)

Decision Diagrams



Exact diagram
Width = 3

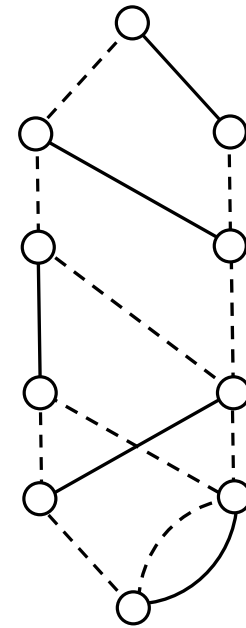
x_1

x_2

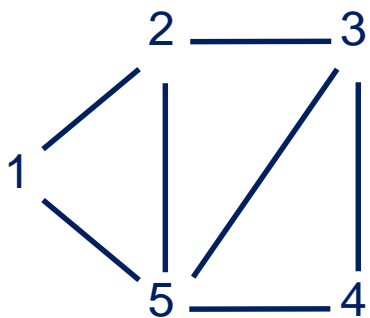
x_3

x_4

x_5



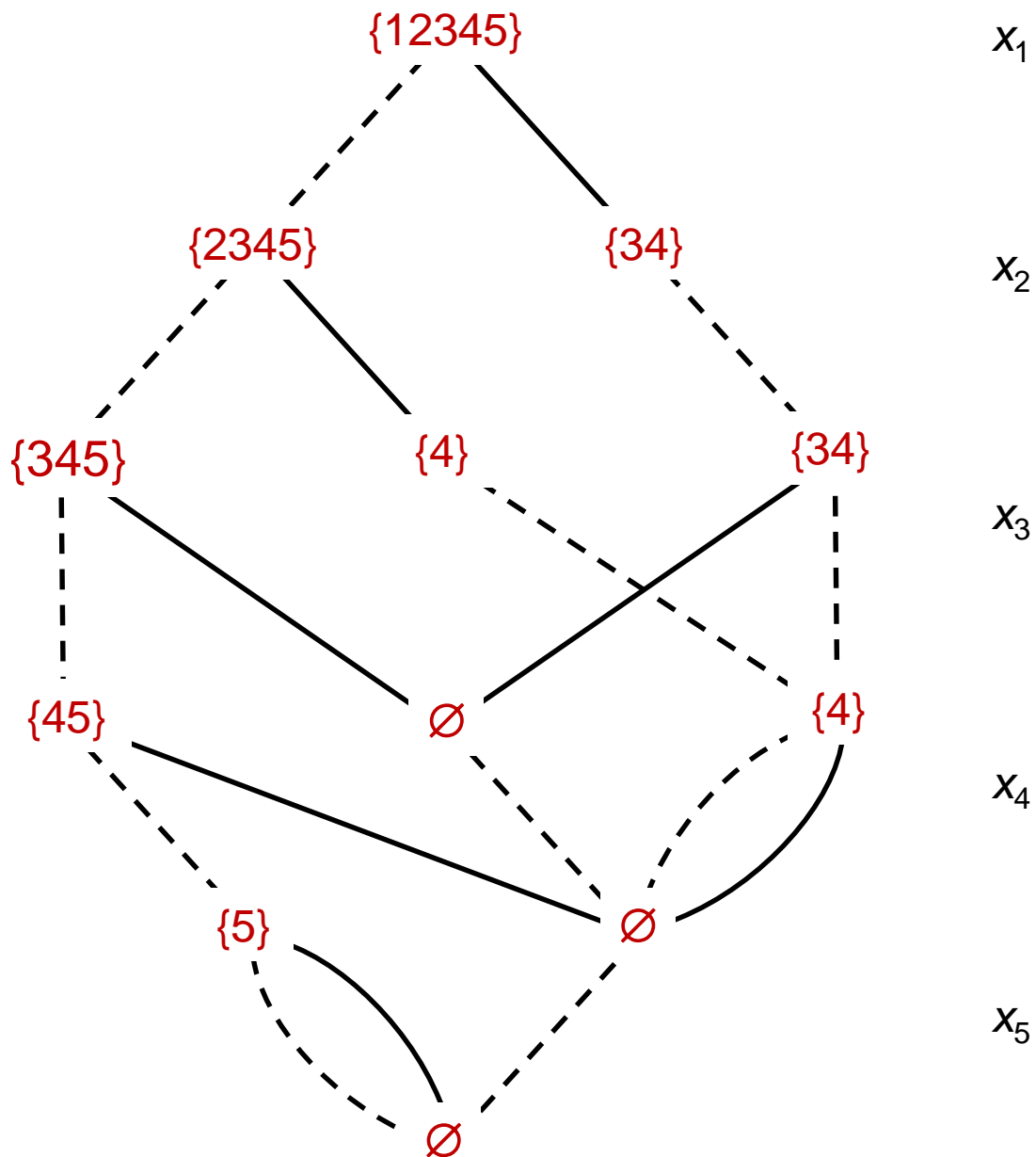
Relaxed diagram
Width = 2

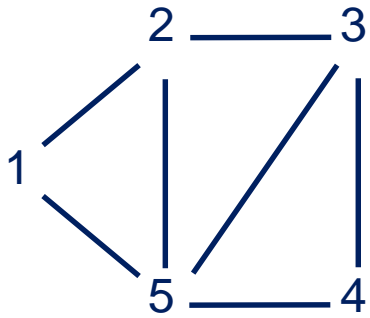


Exact DD for
stable set problem

To build DD,
associate **state**
with each node

--- $x_j = 0$
— $x_j = 1$





{12345}

x_1

x_2

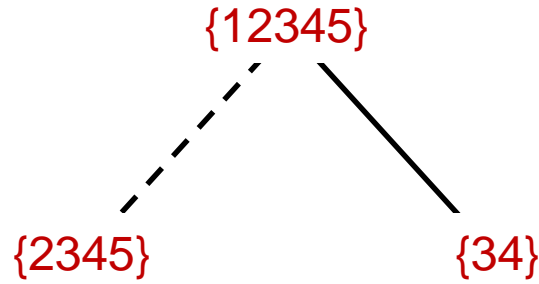
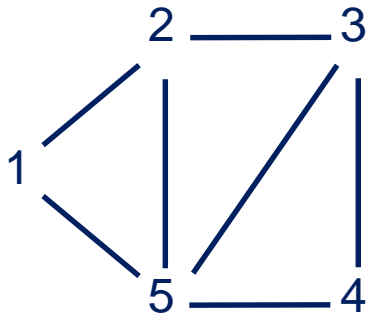
x_3

x_4

x_5

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x_1

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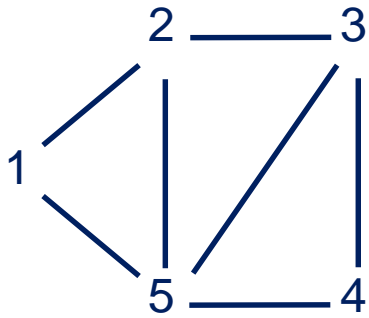
x_3

x_4

x_5

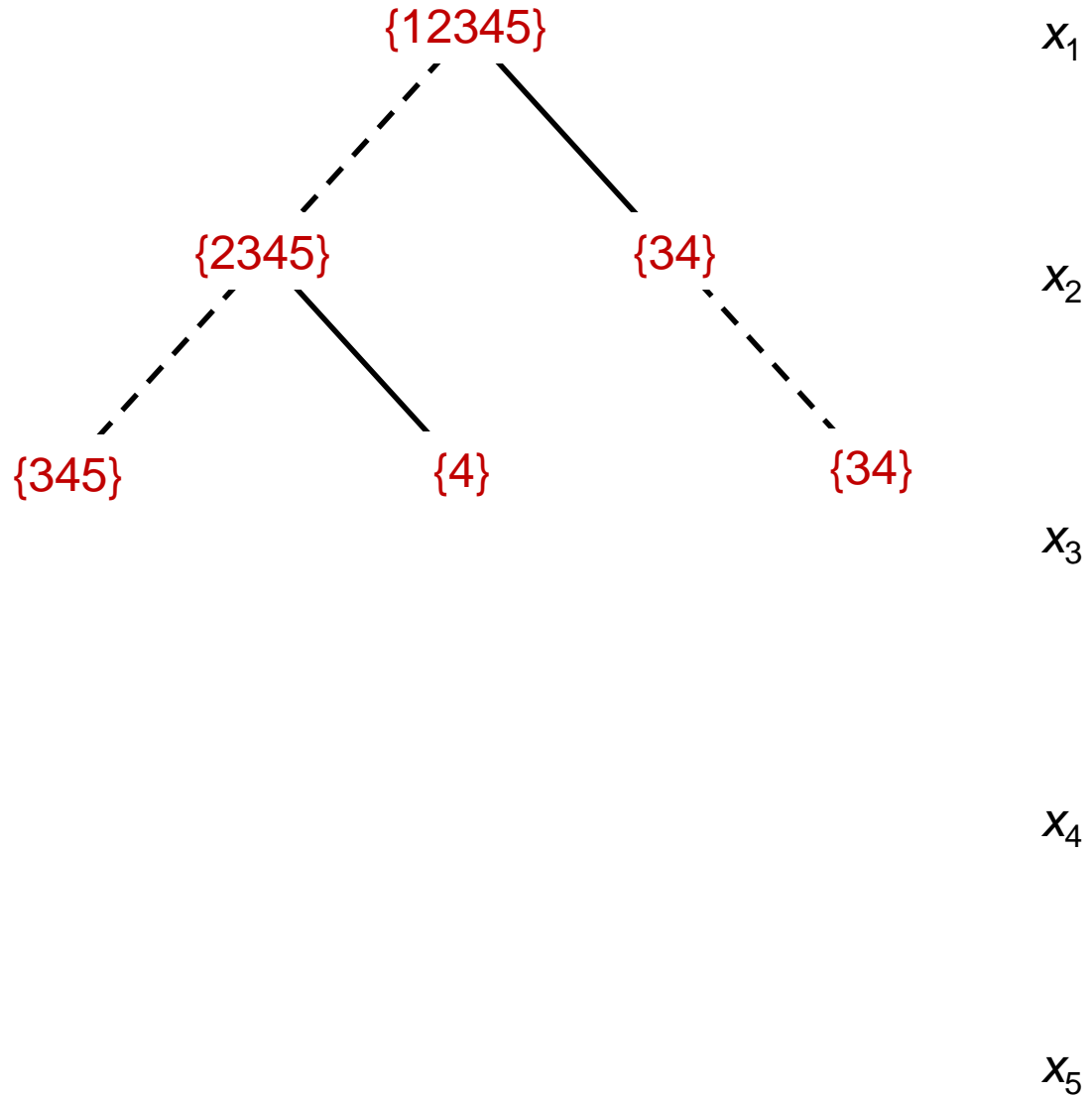
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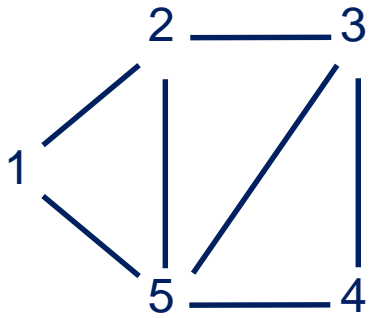
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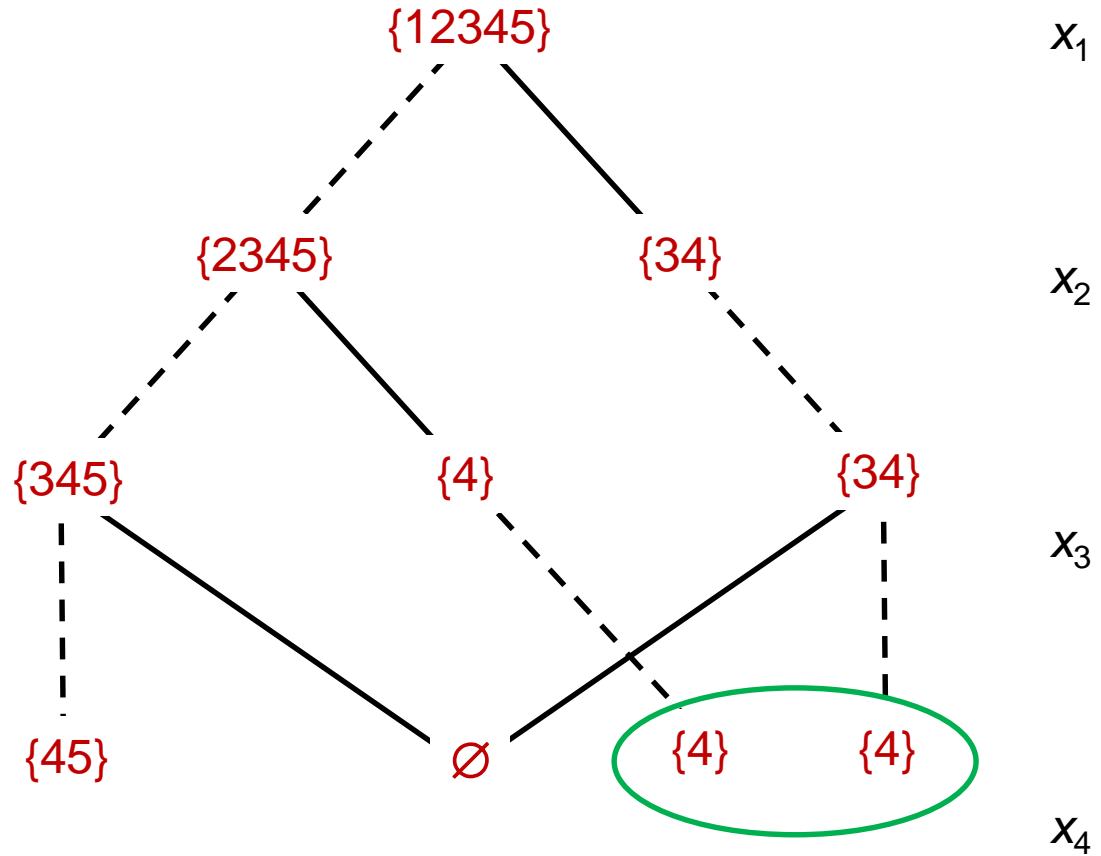
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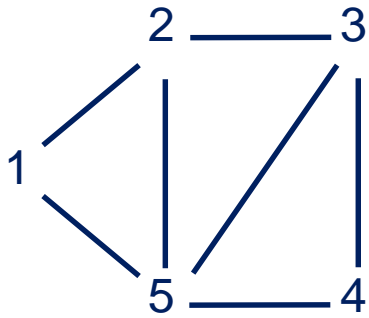


Exact DD for stable set problem

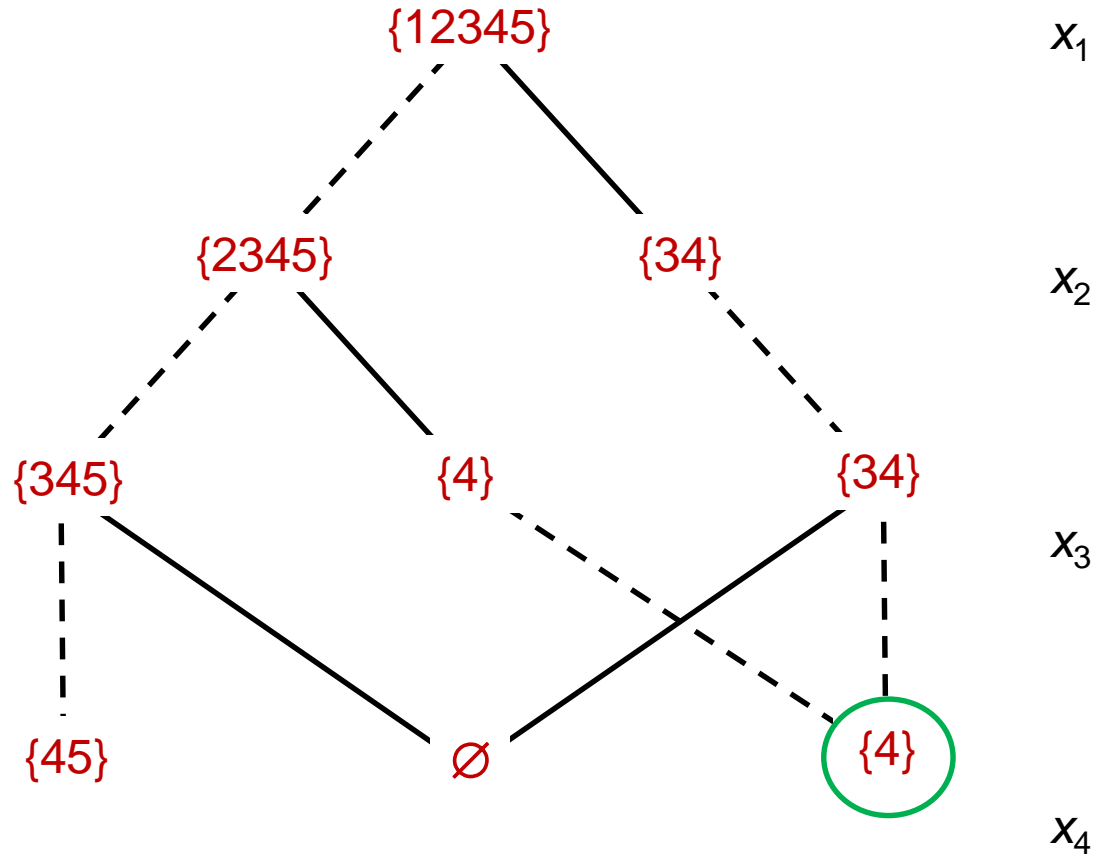


Merge nodes that correspond to the same state

x_1
 x_2
 x_3
 x_4
 x_5

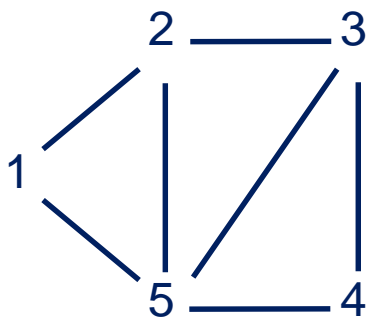


Exact DD for
stable set problem



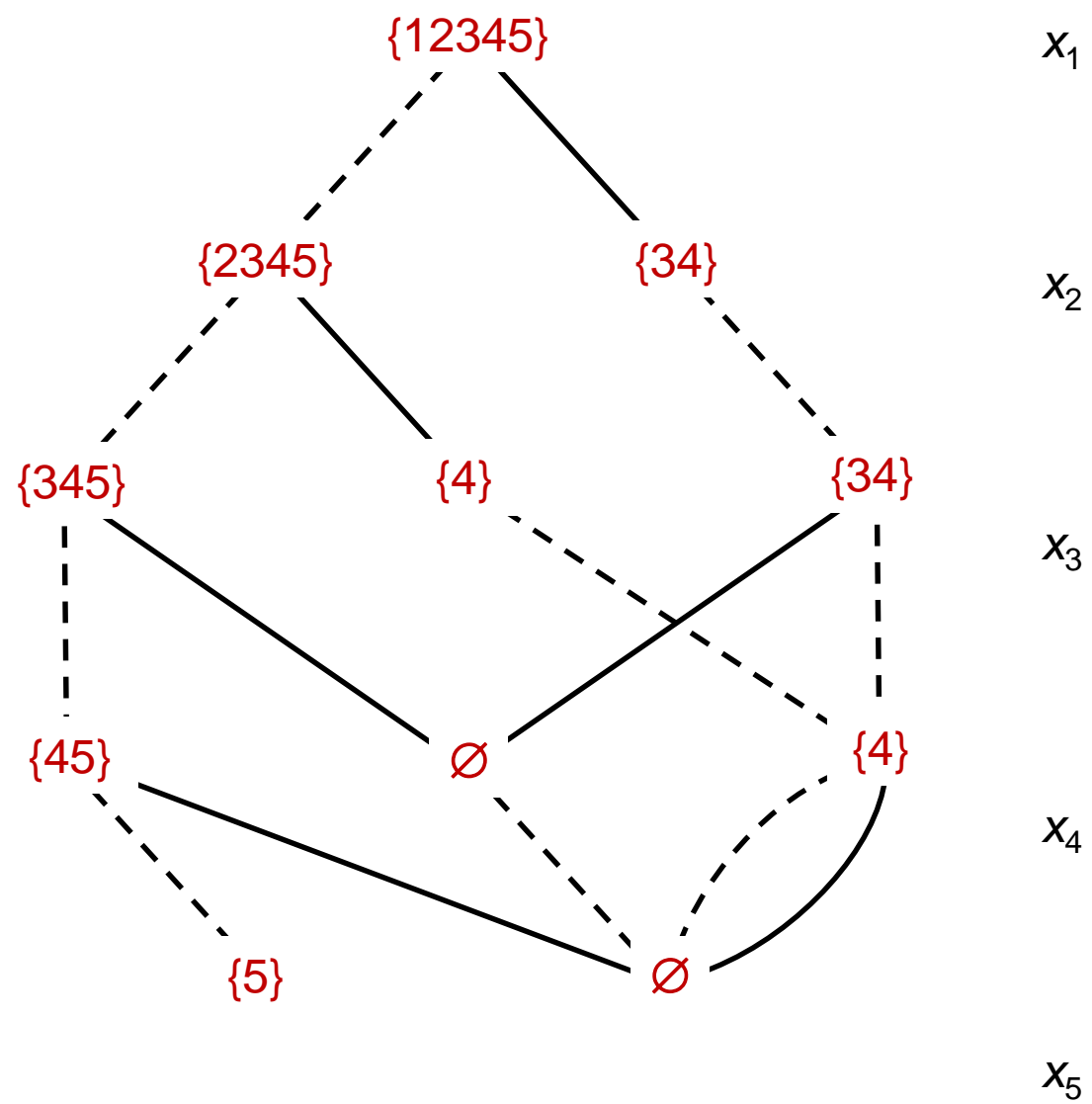
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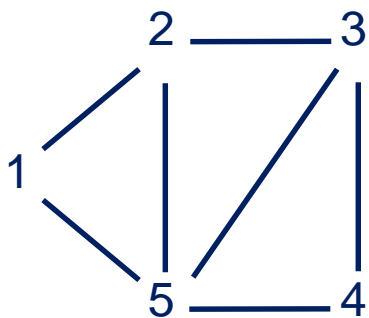
x_5



Exact DD for
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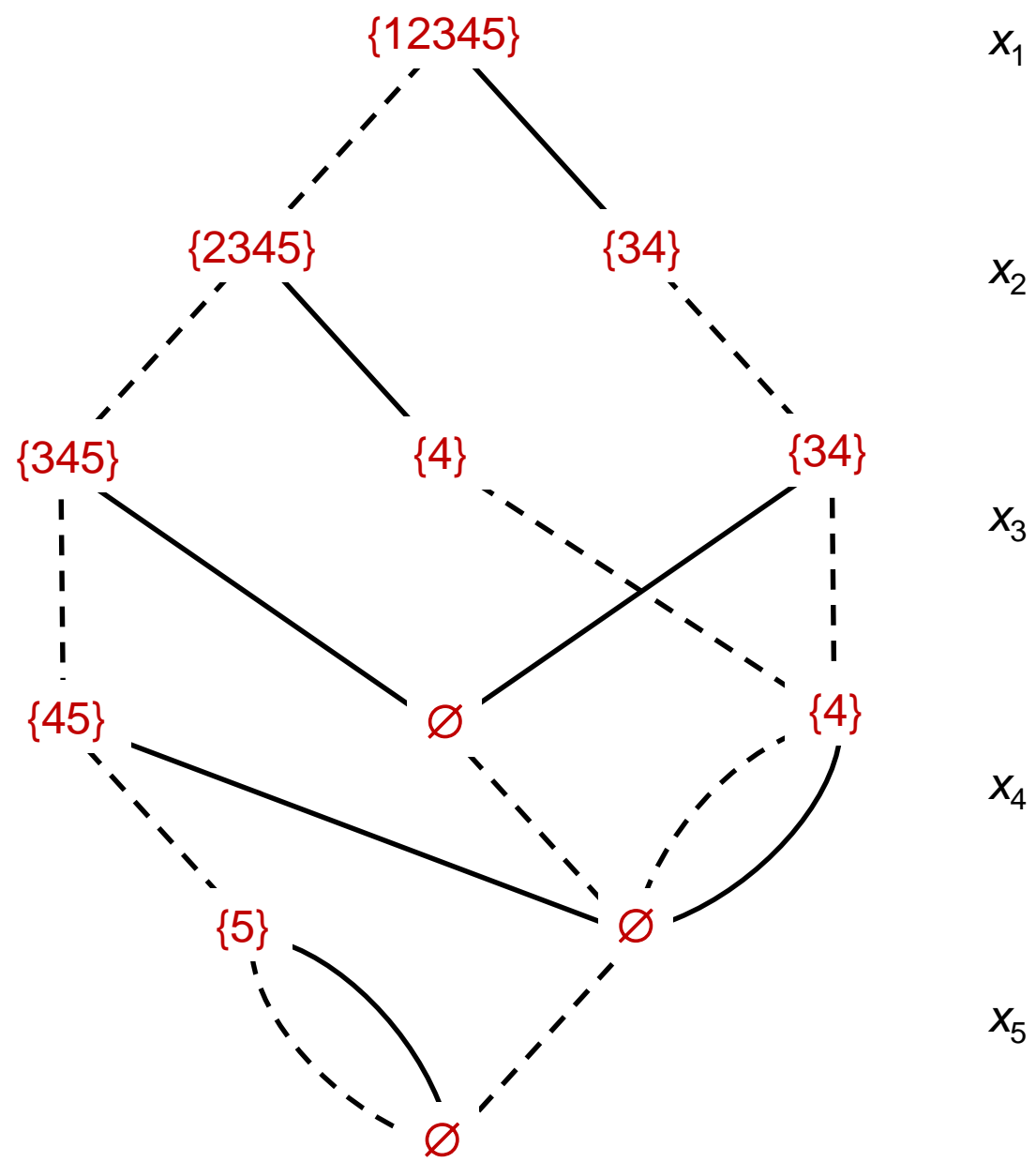
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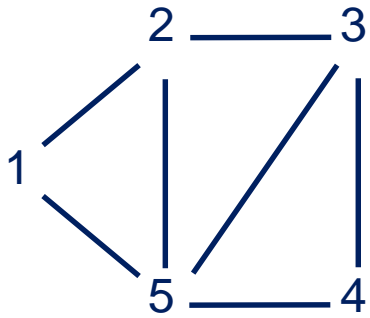
Exact DD for
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To build DD,
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Relaxation Bounding

- To obtain a bound on the objective function:
 - Use a **relaxed** BDD
 - Analogous to LP relaxation in IP
 - This relaxation is **discrete**.
 - Doesn't require the linear inequality formulation of IP.



{12345}

x_1

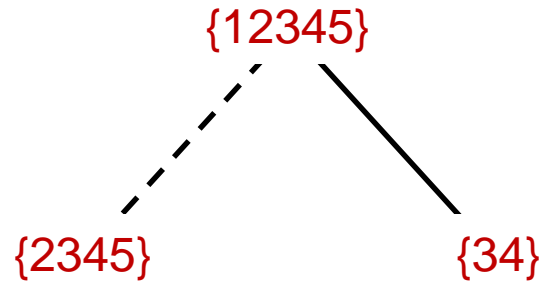
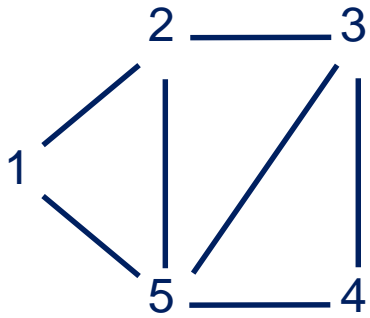
x_2

x_3

x_4

x_5

To build **relaxed**
BDD, merge
some additional
nodes as we go
along



x_1

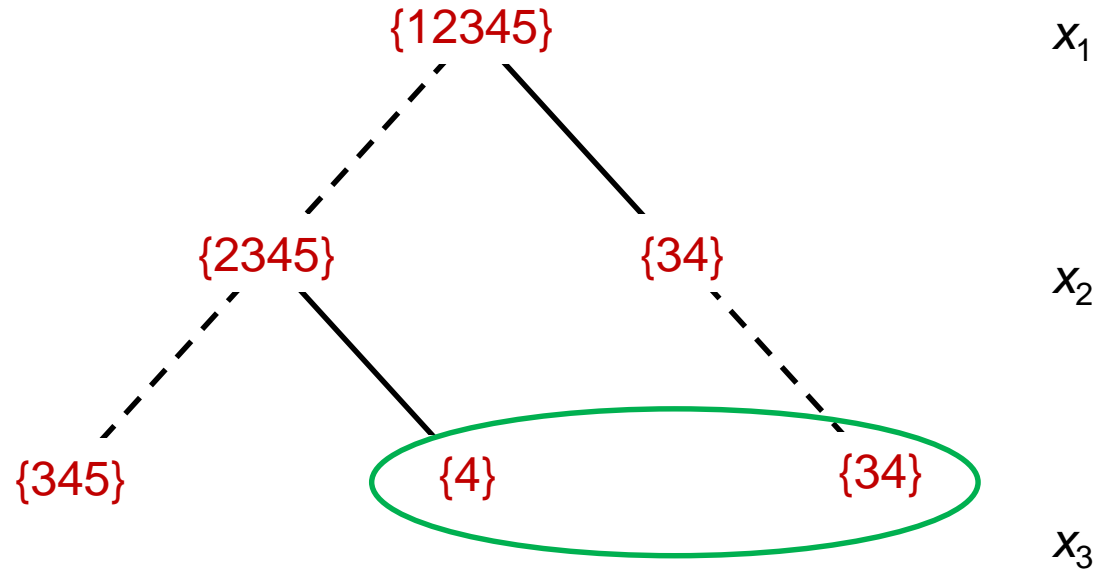
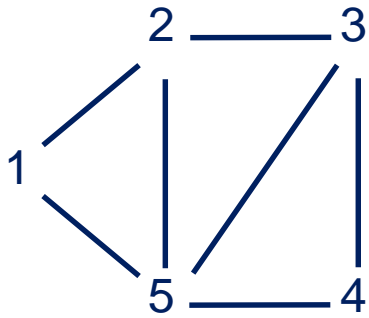
x_2

x_3

x_4

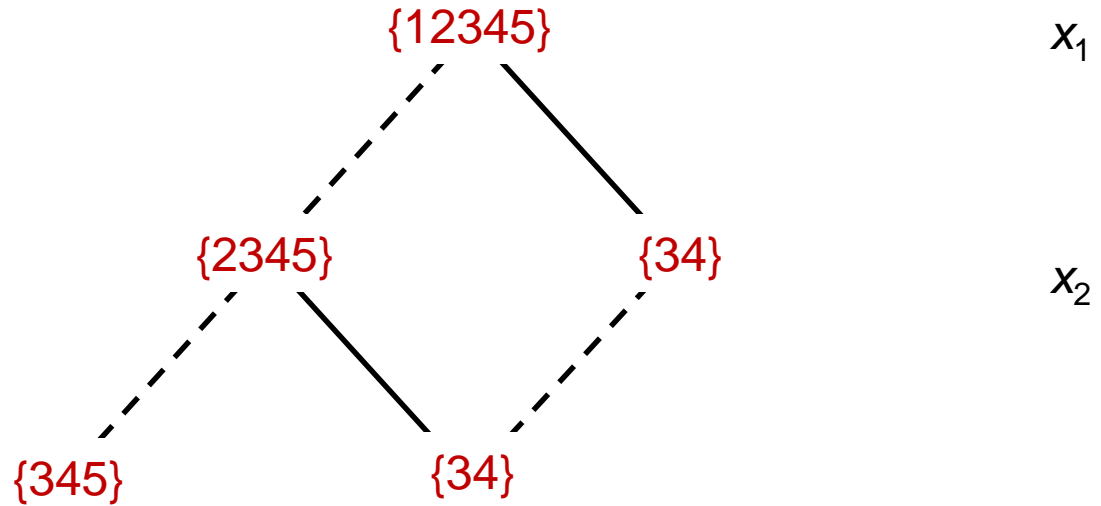
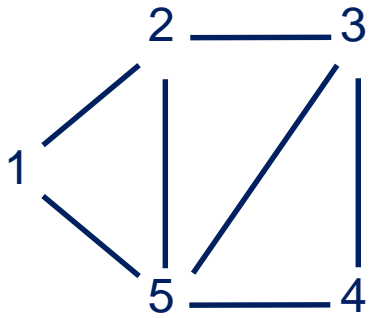
x_5

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x_5



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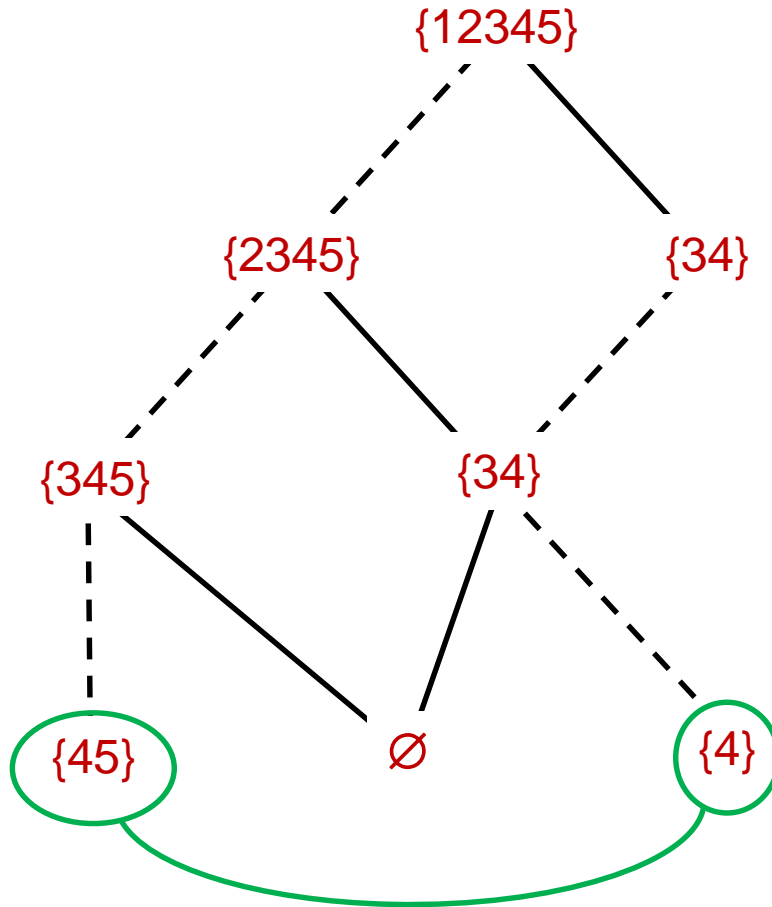
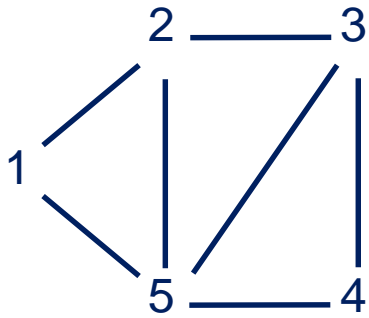
x_2

x_3

x_4

x_5

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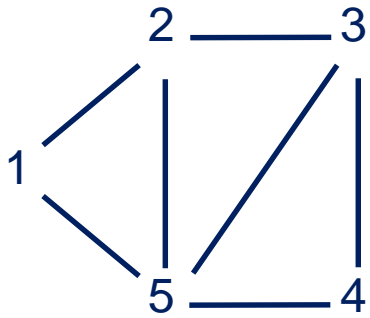
x_2

x_3

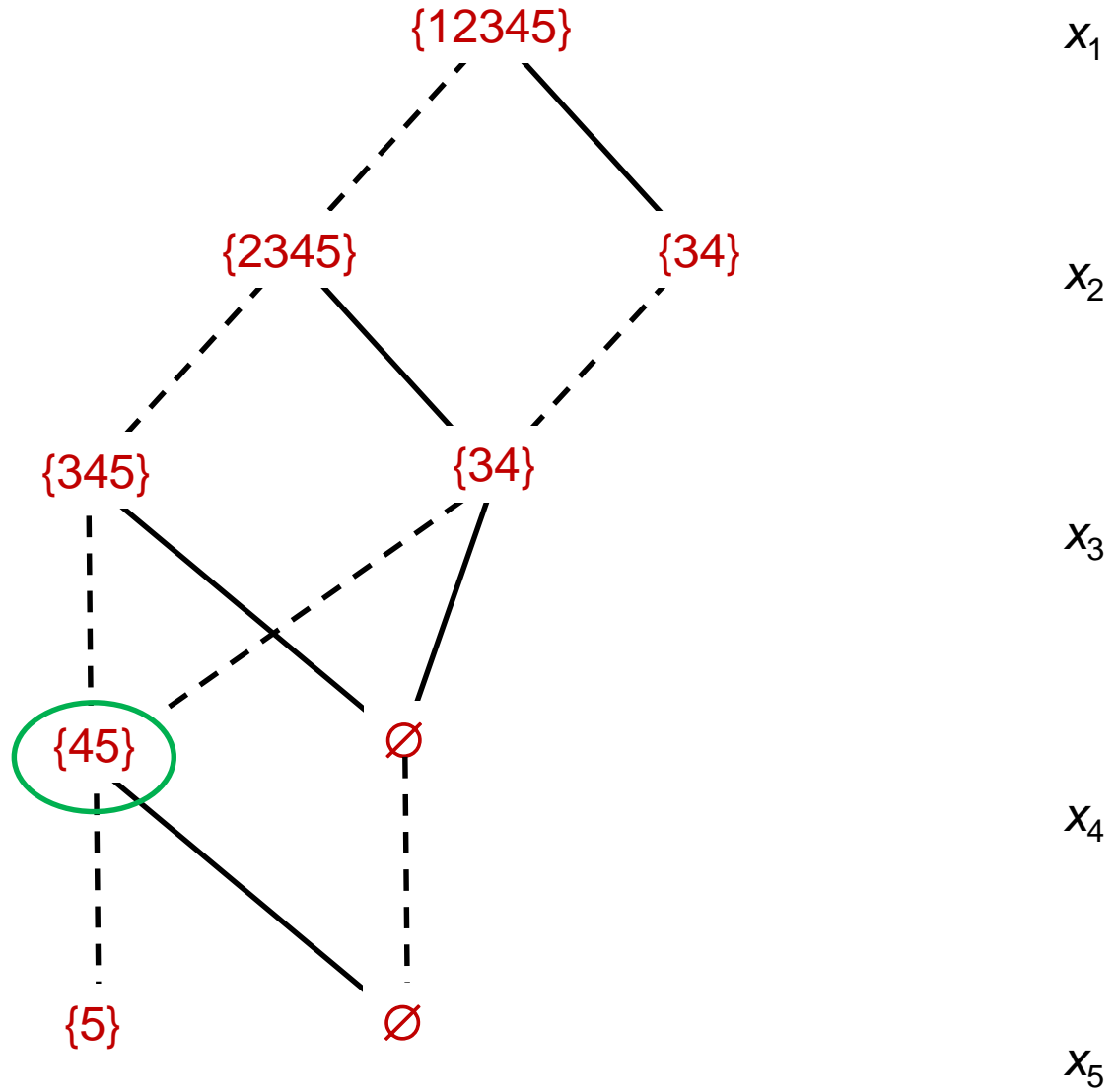
x_4

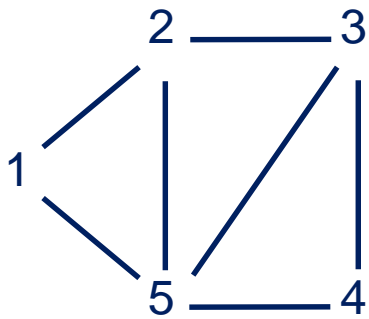
x_5

To build **relaxed** BDD, merge some additional nodes as we go along



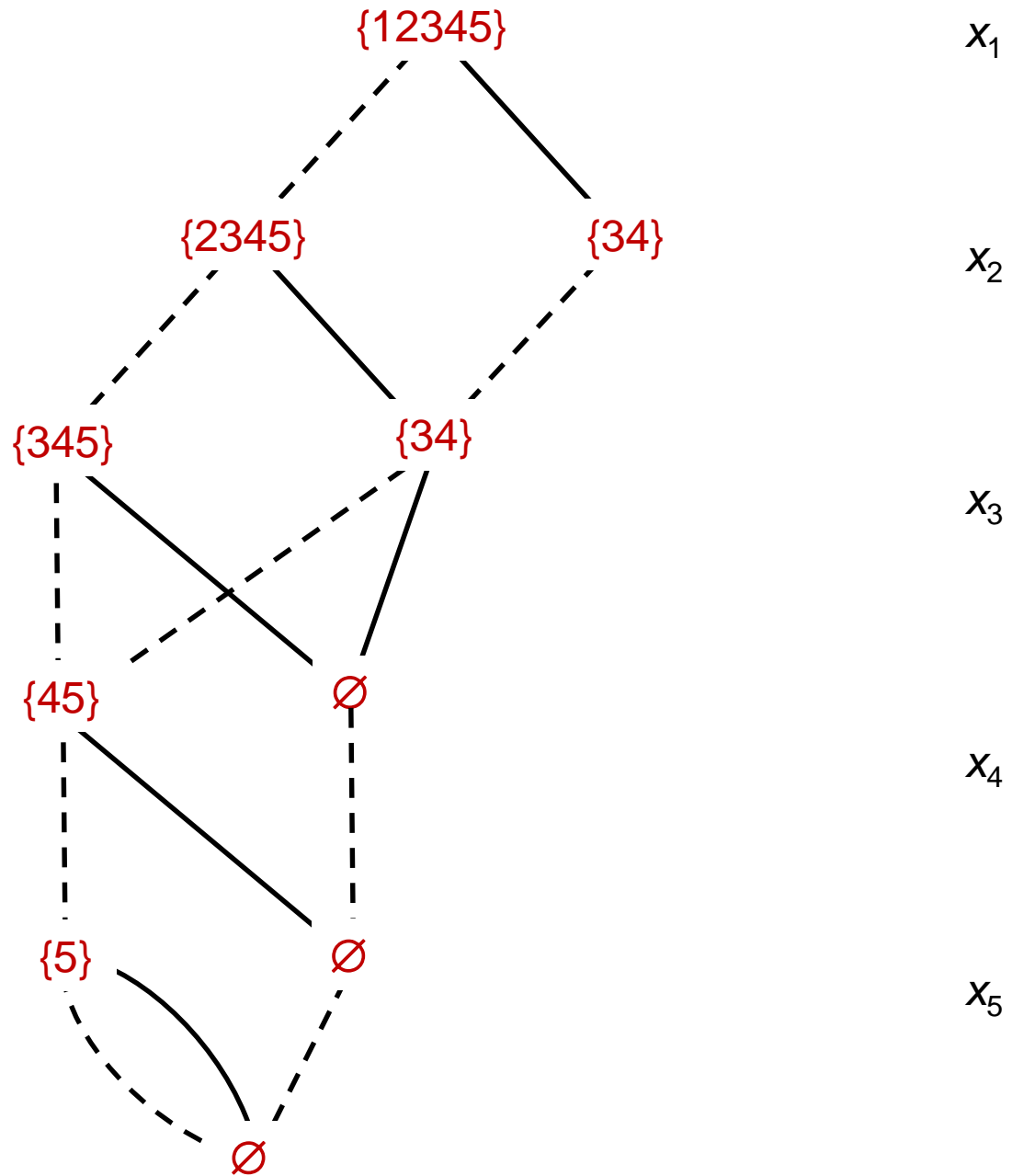
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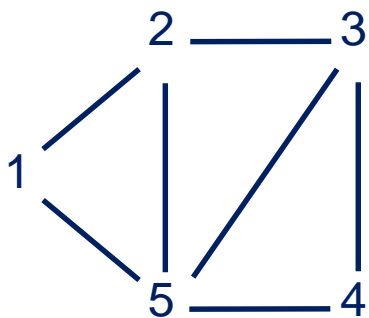




Width = 2

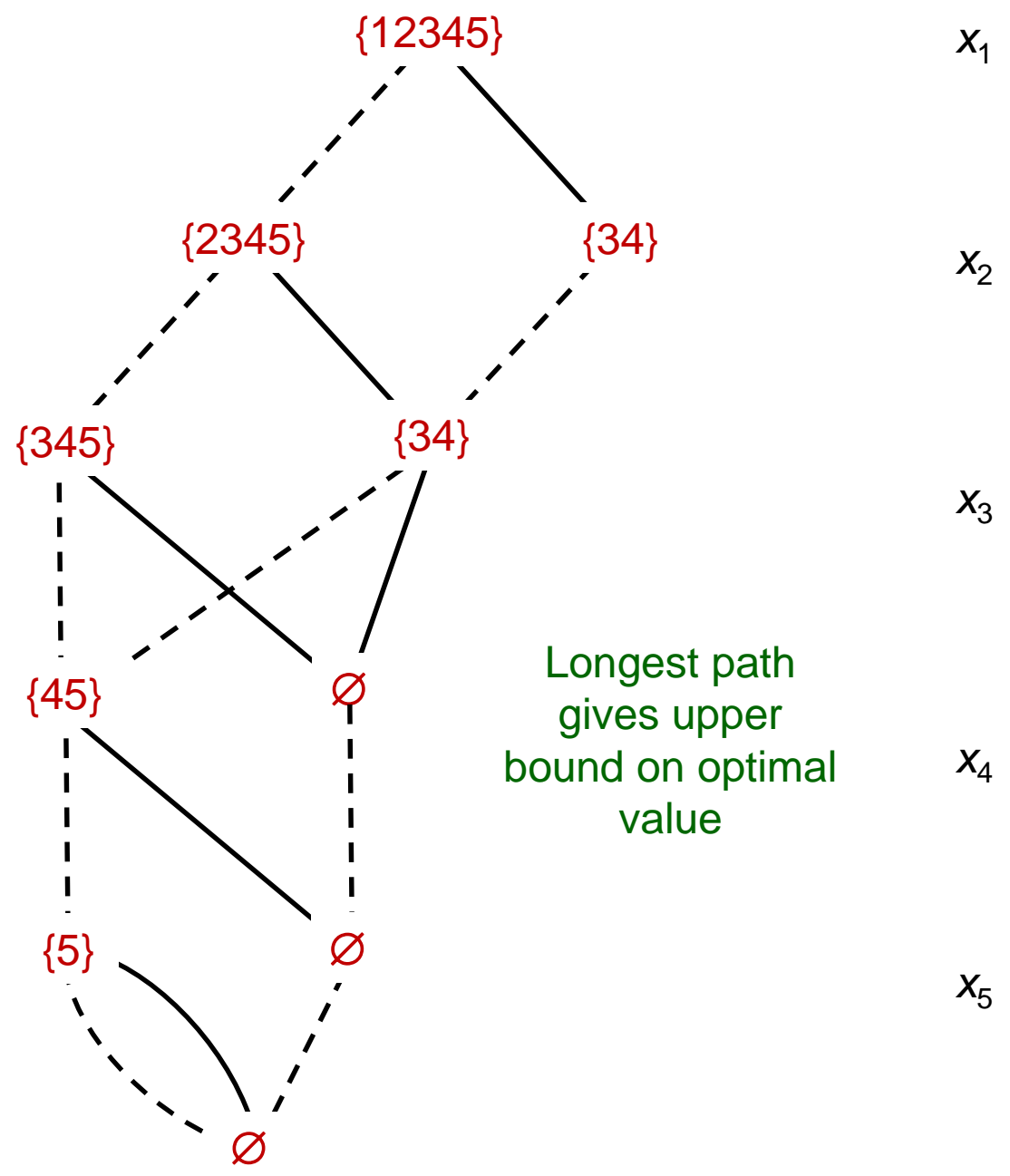
Represents 11 solutions,
including 9
feasible solutions





Width = 2

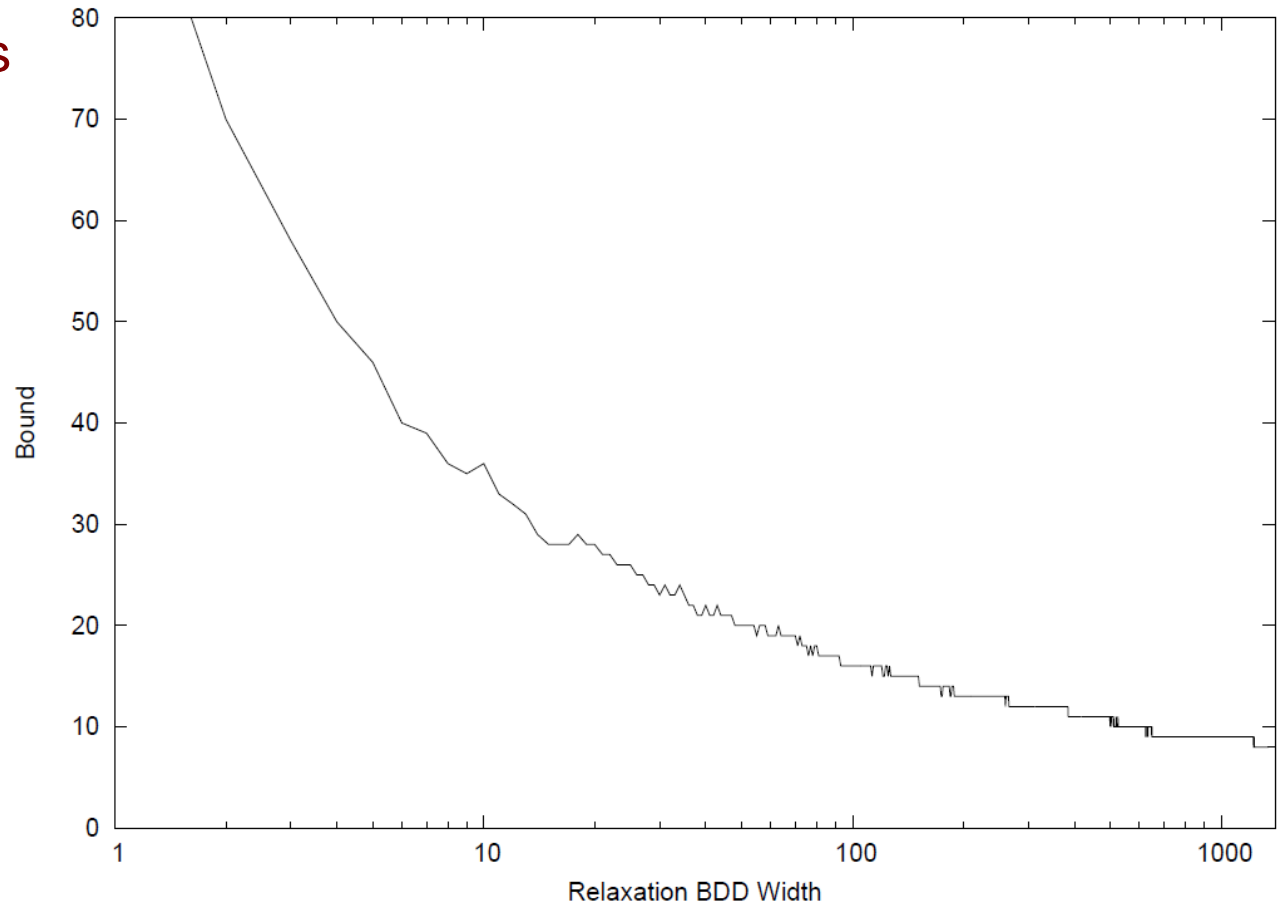
Represents 11 solutions, including 9 feasible solutions



Longest path gives upper bound on optimal value

Decision Diagrams

- Wider diagrams yield tighter bounds
 - But take longer to build.
 - Adjust width dynamically.



Decision Diagrams

- Recursive modeling
 - **Dynamic programming** model of problem, using **state variables**.
 - Using state variables.
 - Rule for **merging states** to create relaxed DD.
 - Analogous to adding valid inequalities in IP.
 - How about **curse of dimensionality**?
 - Solve by **branch and bound** in the relaxed diagram, rather than state space enumeration.

Decision Diagrams

- A novel **branch-and-bound** algorithm.
 - Branch on nodes in **last exact layer** of relaxed decision diagram.
 - ...rather than branch on variables.
 - Create a new **relaxed DD rooted** at each branching node.
 - Prune search tree using bounds from relaxed DD.

Decision Diagrams

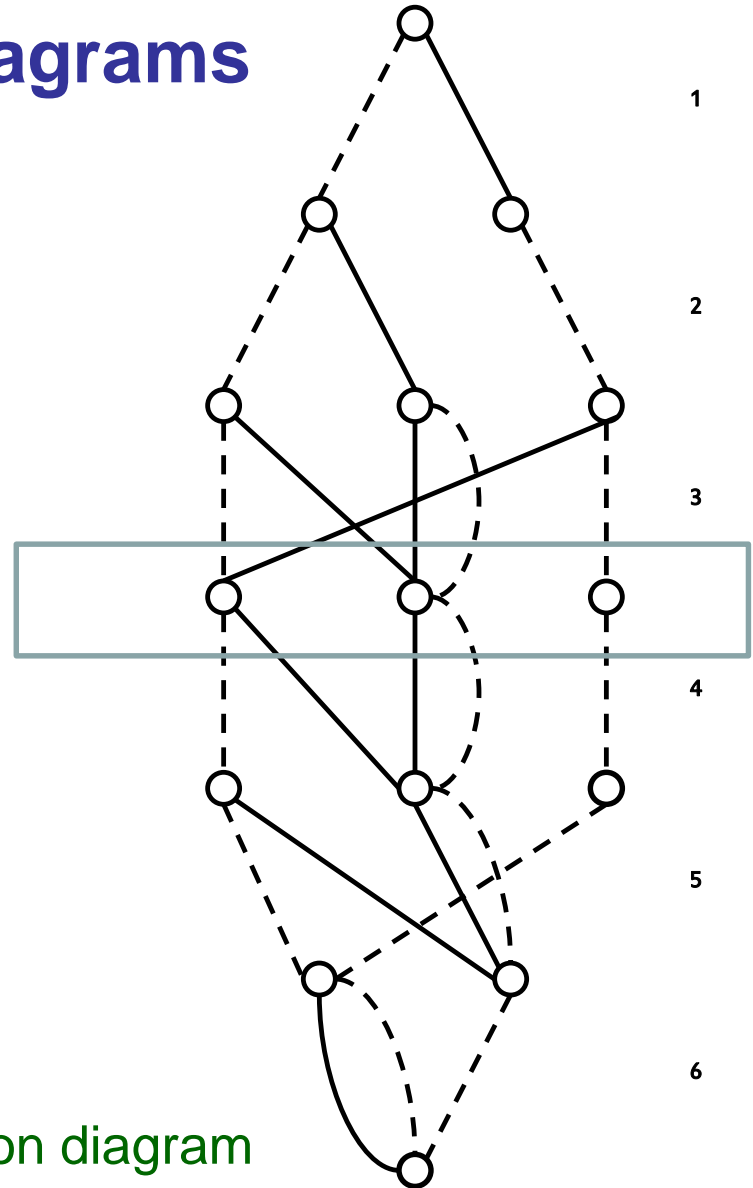
- A novel **branch-and-bound** algorithm.
 - Branch on nodes in **last exact layer** of relaxed decision diagram.
 - ...rather than branch on variables.
 - Create a new **relaxed DD rooted** at each branching node.
 - Prune search tree using bounds from relaxed DD.
 - Advantage: a manageable number states may be reachable in first few layers.
 - ...even if the state space is **exponential**.

Decision Diagrams

Branching in a relaxed decision diagram

Bergman, Ciré, van Hoesve, JH (2014)

Diagram is exact down to here



Relaxed decision diagram

1

2

3

4

5

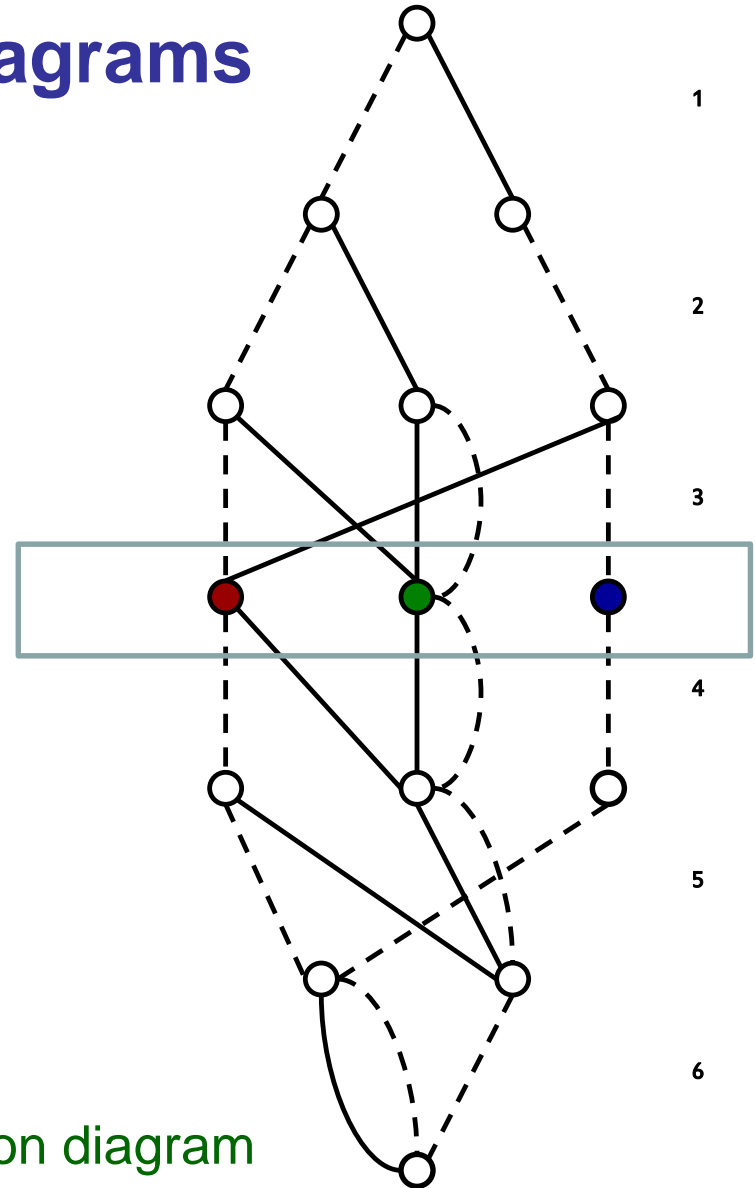
6

Decision Diagrams

Branching in a relaxed decision diagram

Bergman, Ciré, van Hoeve, JH (2014)

Branch on nodes in this layer



Relaxed decision diagram

Decision Diagrams

1

Branching in a relaxed
decision diagram

2

Bergman, Ciré, van Hoeve, JH (2014)

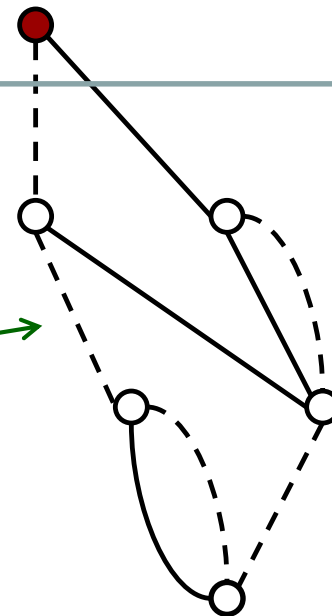
3

First branch



4

New relaxed decision diagram



5

6

35

Decision Diagrams

1

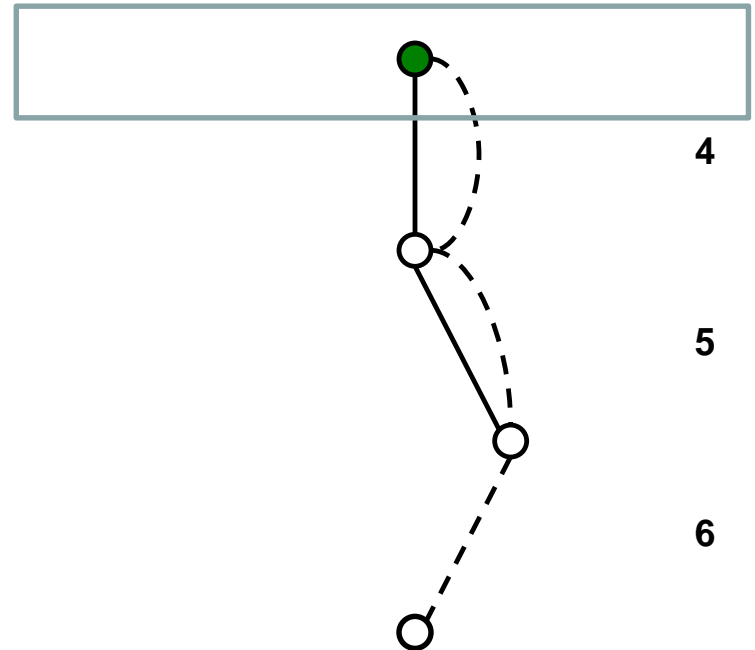
Branching in a relaxed
decision diagram

2

Bergman, Ciré, van Hoeve, JH (2014)

3

Second branch



4

5

6

36

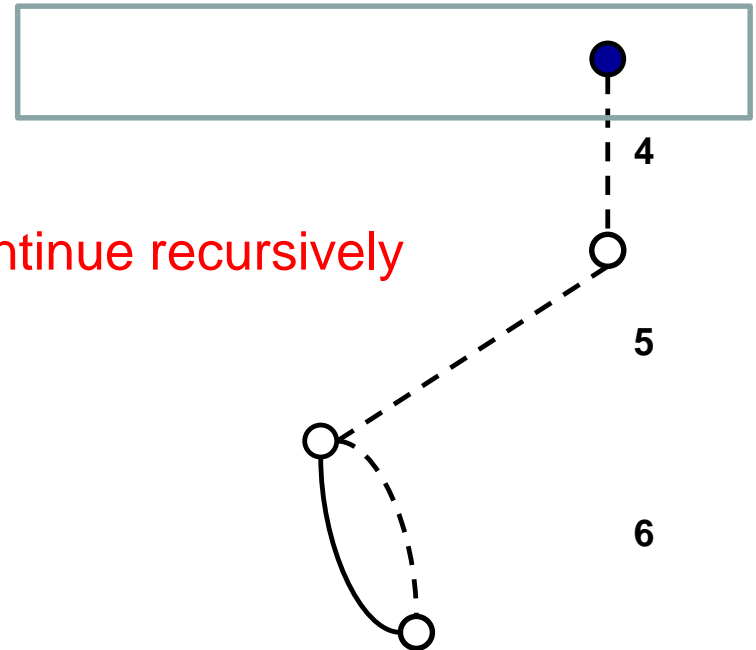
Decision Diagrams

Branching in a relaxed
decision diagram

Bergman, Ciré, van Hoeve, JH (2014)

Third branch

Continue recursively



1

2

3

4

5

6

37

Decision Diagrams

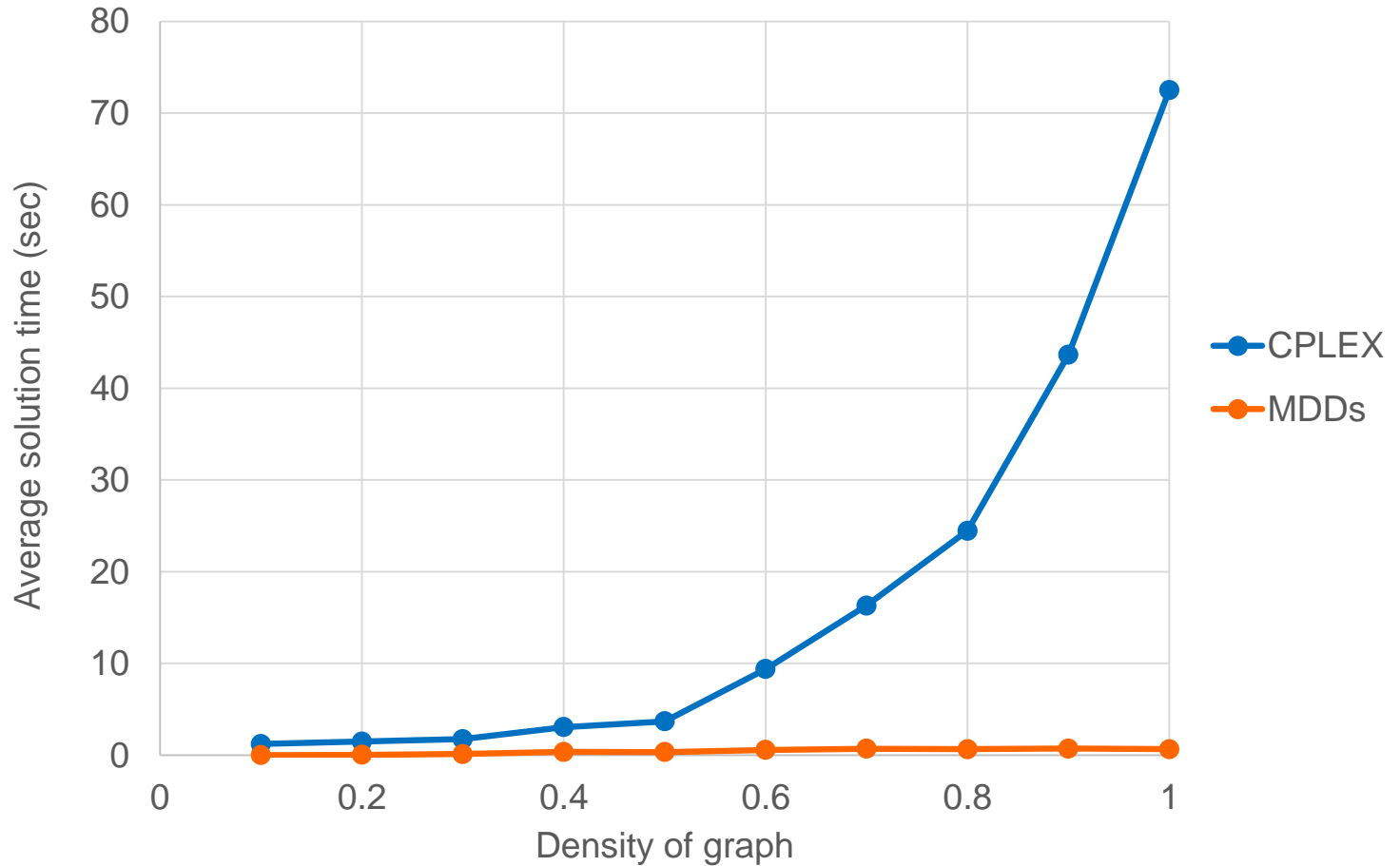
- Computational results for optimization.
 - Stable set, max cut, max 2-SAT.
 - Superior to commercial MIP solver (CPLEX) on most instances.
 - Even though the problems have **natural MIP models**.
 - Obtained best known solution on some max cut instances.
 - Slightly slower than MIP on stable set with precomputed clique cover model, but...

Decision Diagrams

Max cut
on a graph

Avg. solution time
vs
graph density

30 vertices

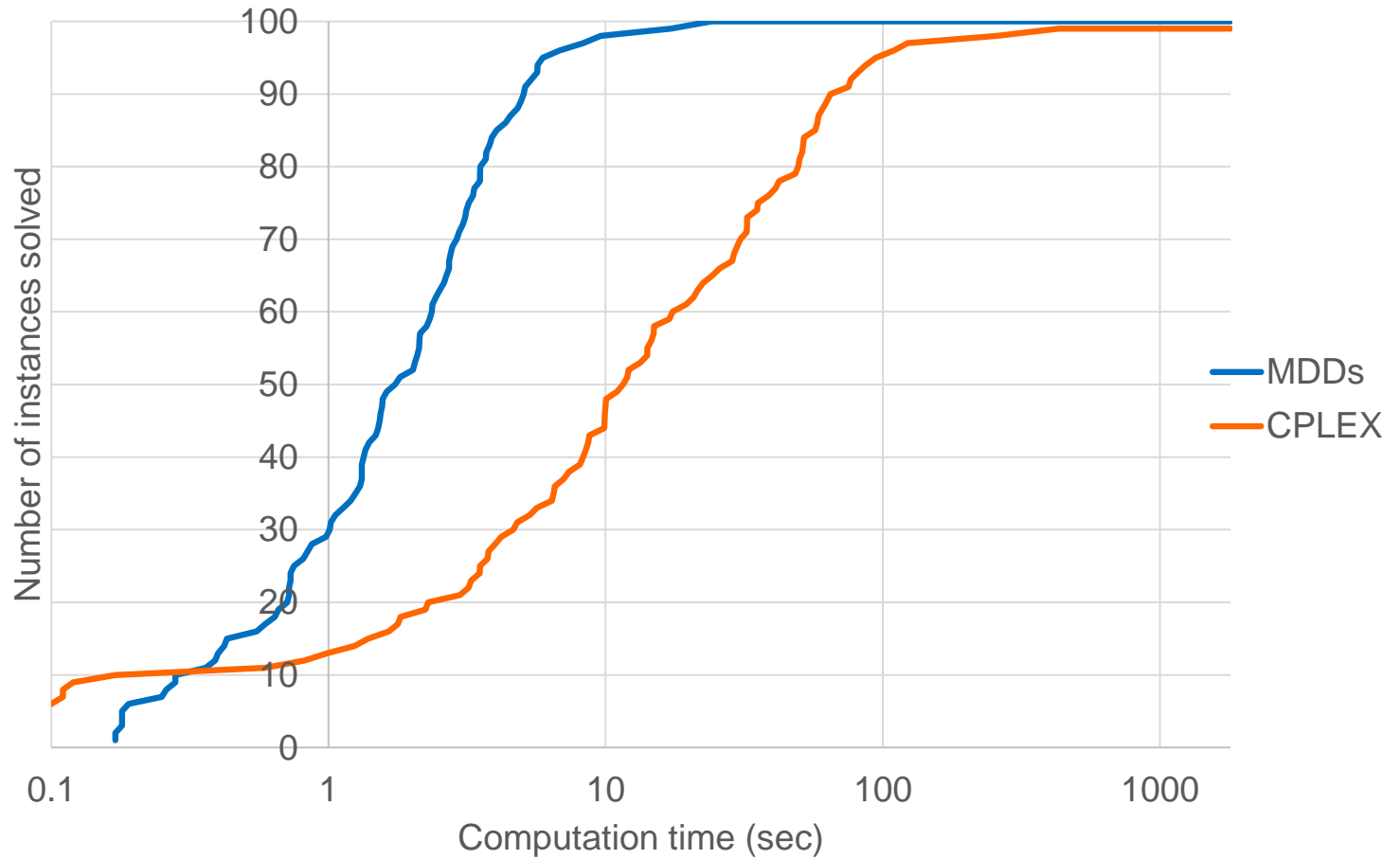


Decision Diagrams

Max 2-SAT

Performance profile

30 variables

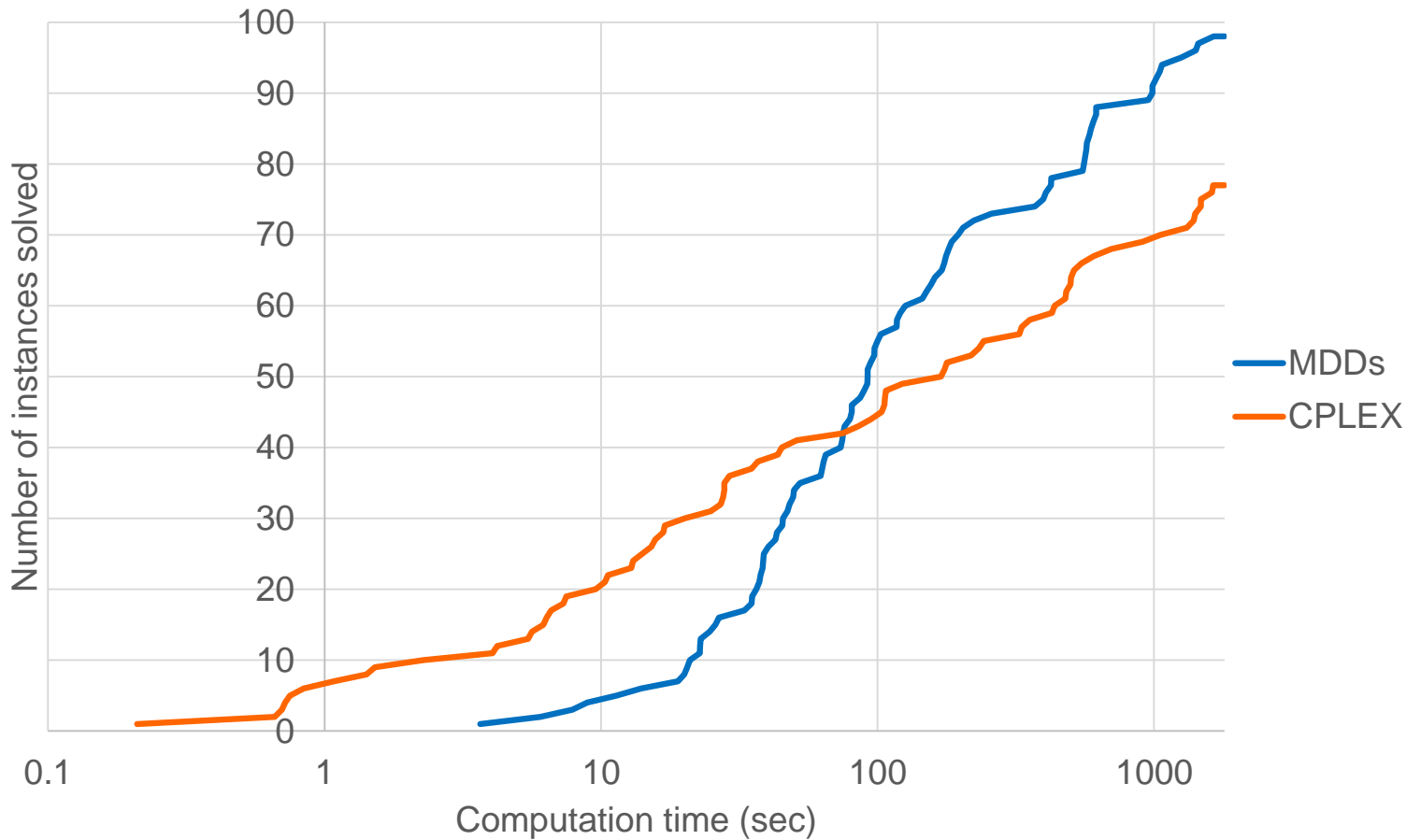


Decision Diagrams

Max 2-SAT

Performance
profile

40 variables



Decision Diagrams

- Potential to scale up
 - No need to load large inequality model into solver.
 - Parallelizes very effectively
 - Near-linear speedup.
 - Much better than mixed integer programming.

Decision Diagrams

- Next steps
 - Decision diagram technology is ready for **large-scale** applications from industry
 - ...which will also help develop the technology.

Decision Diagrams

- Next steps
 - Decision diagram technology is ready for **large-scale** applications from industry
 - ...which will also help develop the technology.
 - Give problems a **dynamic programming** model.
 - ...natural for many applications.
 - But solve by **branch and bound**, not DP.
 - Extend to **stochastic** DP and optimal control.
 - Current research.

Logic-Based Benders

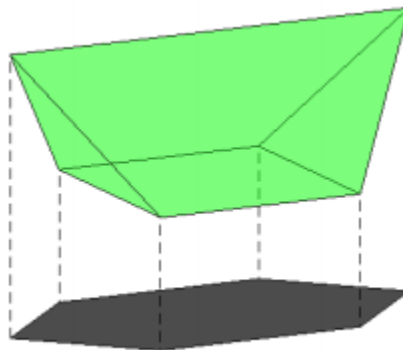
- **Logic-based Benders decomposition** is a generalization of classical Benders decomposition.

JH (1995)

JH and Yan (1995)

JH and Ottosson (2003)

- Solves a **projection** problem.
 - ...and therefore a **logical inference** problem.



Logic-Based Benders

- Collaborators...
 - André Ciré
 - Elvin Çoban
 - Aliza Heching
 - Greger Ottosson
 - Erlendur Thorsteinsson*
 - Hong Yan

*2001 *Best Paper Award*, CP conference

Logic-Based Benders

- Subproblem is an **arbitrary optimization** problem.
 - In classical Benders, subproblem must be linear or nonlinear programming problem.
 - LBBD replaces LP dual with **inference dual**.
 - Solves problems of the form

$$\begin{aligned} \min & f(x, y) \\ & (x, y) \in S \\ & x \in D \end{aligned}$$

Logic-Based Benders

- Decompose problem into master and subproblem.
 - Subproblem is obtained by fixing x to solution value in master problem.

Master problem

$$\begin{aligned} \min z \\ z \geq g_k(x) \quad (\text{Benders cuts}) \\ x \in D \end{aligned}$$

Find x that minimizes cost z subject to Benders cuts obtained from solutions in previous iterations k .

→
Trial value \bar{x}
that solves
master

←
Benders cut
 $z \geq g_k(x)$

Subproblem

$$\begin{aligned} \min f(\bar{x}, y) \\ (\bar{x}, y) \in S \end{aligned}$$

Obtain proof of optimality (**inference dual**).
Use same proof to deduce cost bounds for other assignments, yielding **Benders cut**.

Logic-Based Benders

- Iterate until master problem value equals best subproblem value so far.
 - This yields optimal solution.

Master problem

$$\begin{aligned} \min z \\ z \geq g_k(x) \quad (\text{Benders cuts}) \\ x \in D \end{aligned}$$

Find x that minimizes cost z subject to Benders cuts obtained from solutions in previous iterations k .

→ Trial value \bar{x} that solves master

← Benders cut $z \geq g_k(x)$

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Logic-Based Benders

- Substantial speedup for many applications.
 - Several orders of magnitude relative to state of the art.

Logic-Based Benders

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 - Several orders of magnitude relative to state of the art.
- Some applications:
 - Circuit verification
 - Chemical batch processing (BASF, etc.)
 - Steel production scheduling
 - Auto assembly line management (Peugeot-Citroën)
 - Automated guided vehicles in flexible manufacturing
 - Allocation and scheduling of multicore processors (IBM, Toshiba, Sony)
 - Facility location-allocation
 - Stochastic facility location and fleet management
 - Capacity and distance-constrained plant location

Logic-Based Benders

- Some applications...
 - Transportation network design
 - Traffic diversion around blocked routes
 - Worker assignment in a queuing environment
 - Single- and multiple-machine allocation and scheduling
 - Permutation flow shop scheduling with time lags
 - Resource-constrained scheduling
 - Wireless local area network design
 - Service restoration in a network
 - Optimal control of dynamical systems
 - Sports scheduling

Logic-Based Benders

- Application to planning and scheduling.
 - Assign tasks in master, schedule them in subproblem.
 - Combine **mixed integer programming (MIP)** and **CP**

Master problem

Assign tasks to resources to minimize cost.

Solve by **MIP**.

→
Trial
assignment
 \bar{x}

←
Benders cut
 $z \geq g_k(x)$

Subproblem

Schedule tasks on each resource, subject to time windows.

CP obtains proof of optimality (inference dual).

Use **same proof** to deduce cost for other assignments, yielding **Benders cut**.

Logic-Based Benders

- Objective function

- Cost is based on **task assignment only**.

$$\text{cost} = \sum_{ij} c_{ij} x_{ij}, \quad x_{ij} = 1 \text{ if task } j \text{ assigned to resource } i$$

- So cost appears only in the **master problem**.
- Scheduling subproblem is a **feasibility problem**.

Logic-Based Benders

- Objective function

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- So cost appears only in the **master problem**.
- Scheduling subproblem is a **feasibility problem**.

- Benders cuts

- They have the form $\sum_{j \in J_i} (1 - x_{ij}) \geq 1$, all i

- where J_i is a set of tasks that create infeasibility when assigned to resource i .

Logic-Based Benders

- Resulting Benders decomposition:

Master problem

$$\min z$$
$$z = \sum_{ij} c_{ij} x_{ij}$$

Benders cuts

Subproblem

Schedule jobs on each resource.

CP may obtain proof of infeasibility on some resources (inference dual).

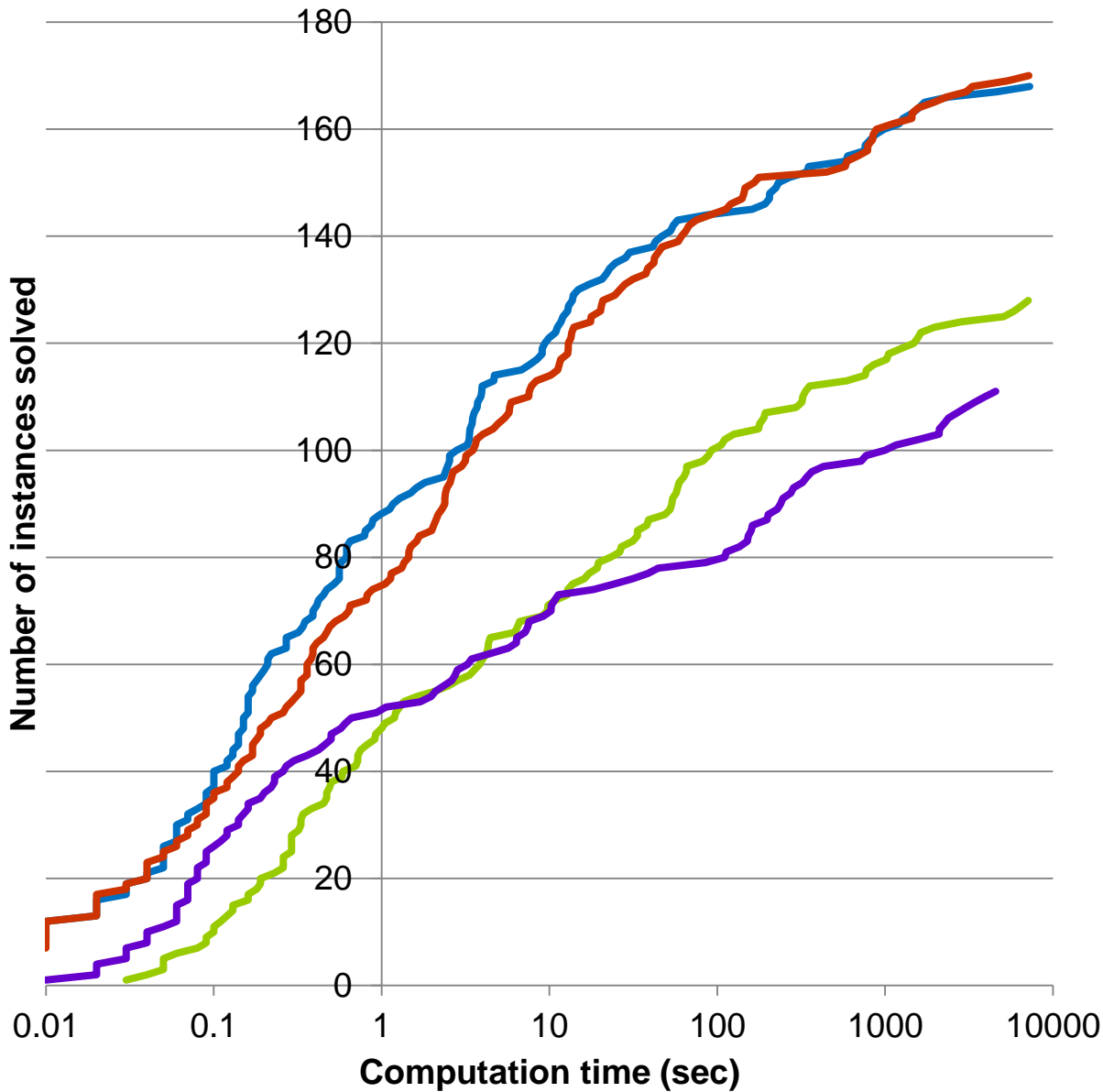
Use **same proof** to deduce infeasibility for some other assignments, yielding **Benders cut**.

→
Trial
assignment
 \bar{x}

←
Benders cuts

$$\sum_{j \in J_i} (1 - x_{ij}) \geq 1,$$

for infeasible resources i



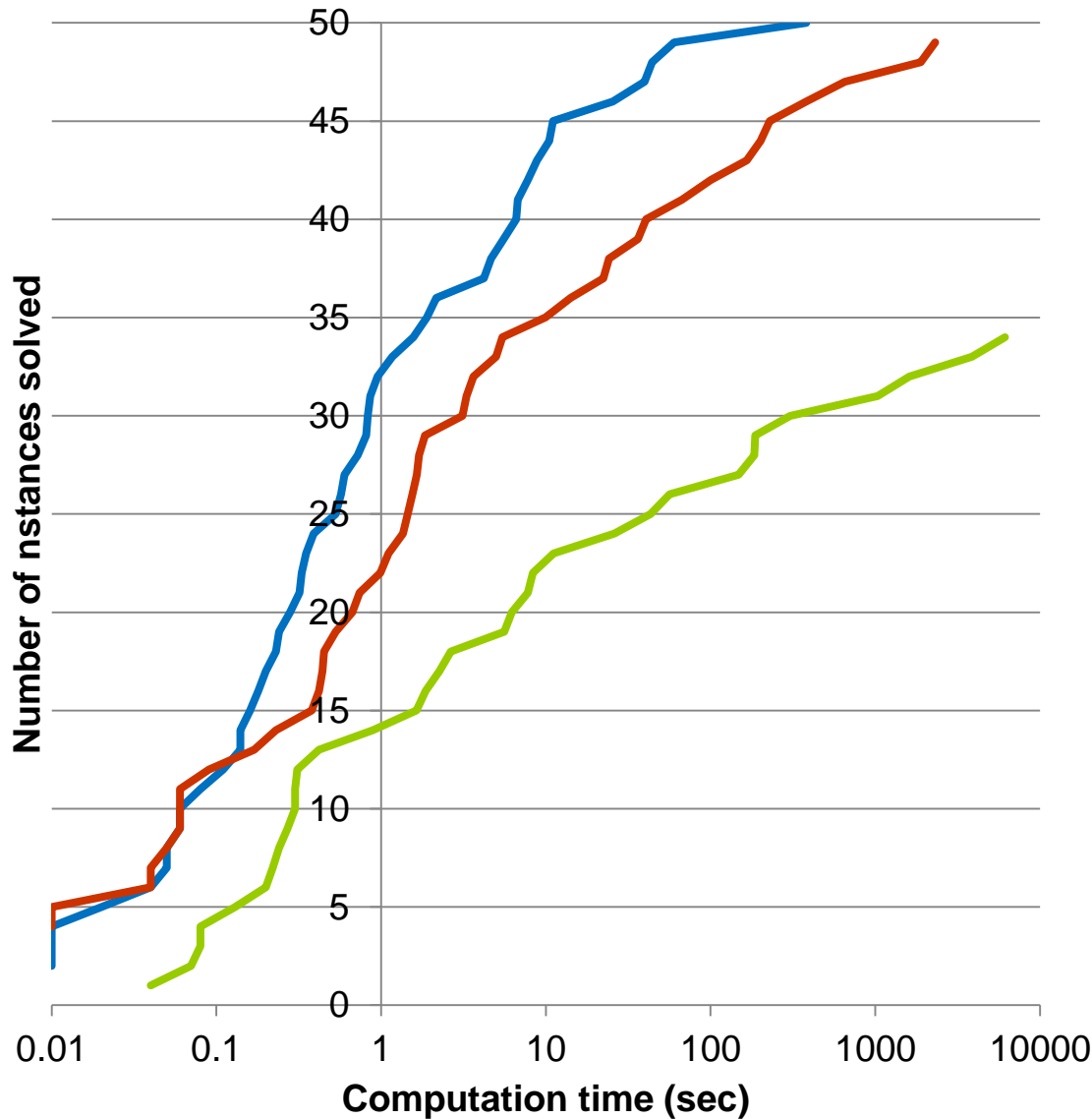
Performance profile

180 instances

Designed to be **hard** for LBB

- Relax + strong cuts
- Relax + weak cuts
- Strong cuts only
- MILP (CPLEX)

MIP is faster than CP



Performance profile

50 instances

More realistic

- Relax + strong cuts
- Relax + weak cuts
- MIP (CPLEX)

MIP is faster than CP

Logic-Based Benders

- Current research
 - Apply to **robust** scheduling.
 - Use a **decision diagram** in the master problem.
 - Apply to **logical inference** from large datasets.

Logic-Based Benders

- Robust scheduling
 - ...with uncertainty sets.
 - Uncertainty subproblem becomes Benders subproblem.
 - IT service center scheduling.
 - Projects subject to uncertain delays
 - Give customers a reasonable worst-case completion date.

Çoban, Heching, JH (2015)



Logic-Based Benders

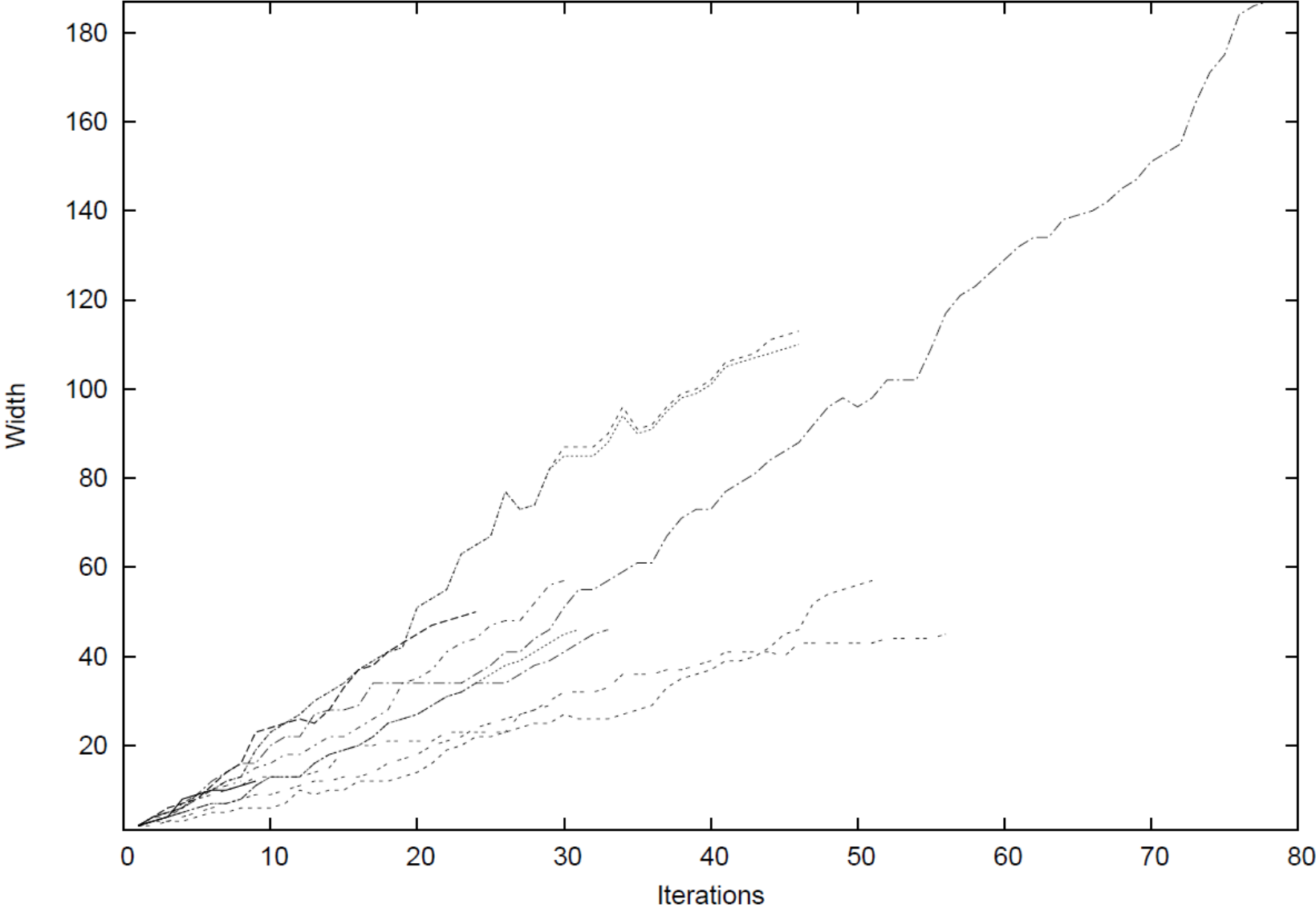
- **Decision diagram** in master problem.
 - Add Benders cuts by **modifying** the decision diagram.
 - Requires **separation algorithm** for decision diagrams
 - Home healthcare scheduling.
 - Master problem assigns healthcare aides to patients.
 - Subproblem schedules visits and routes the aides.
 - **Key question:**
 - How much will the decision diagram **grow** as Benders cuts are added?



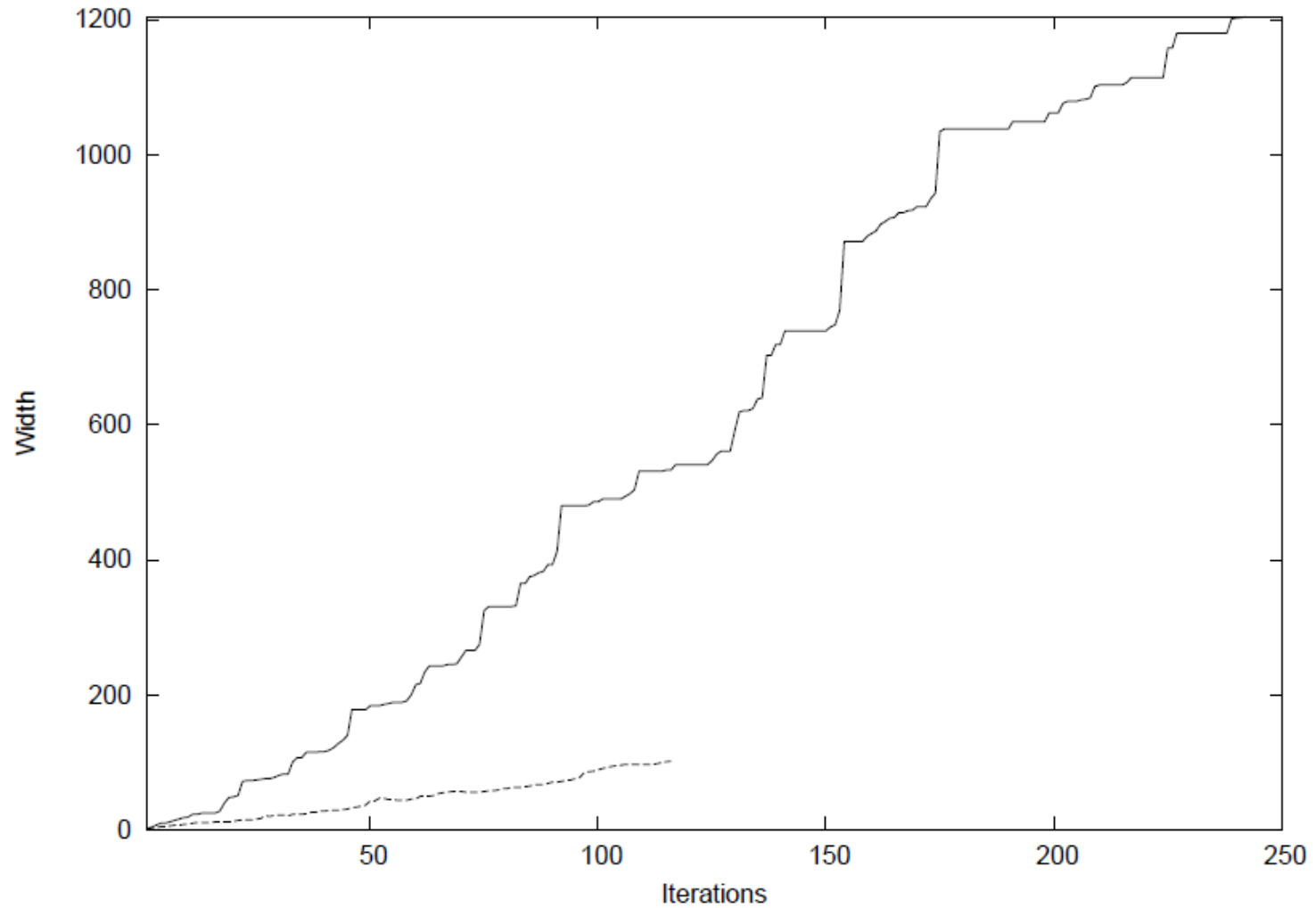
Ciré, JH (2014)

Heching, JH (2015)

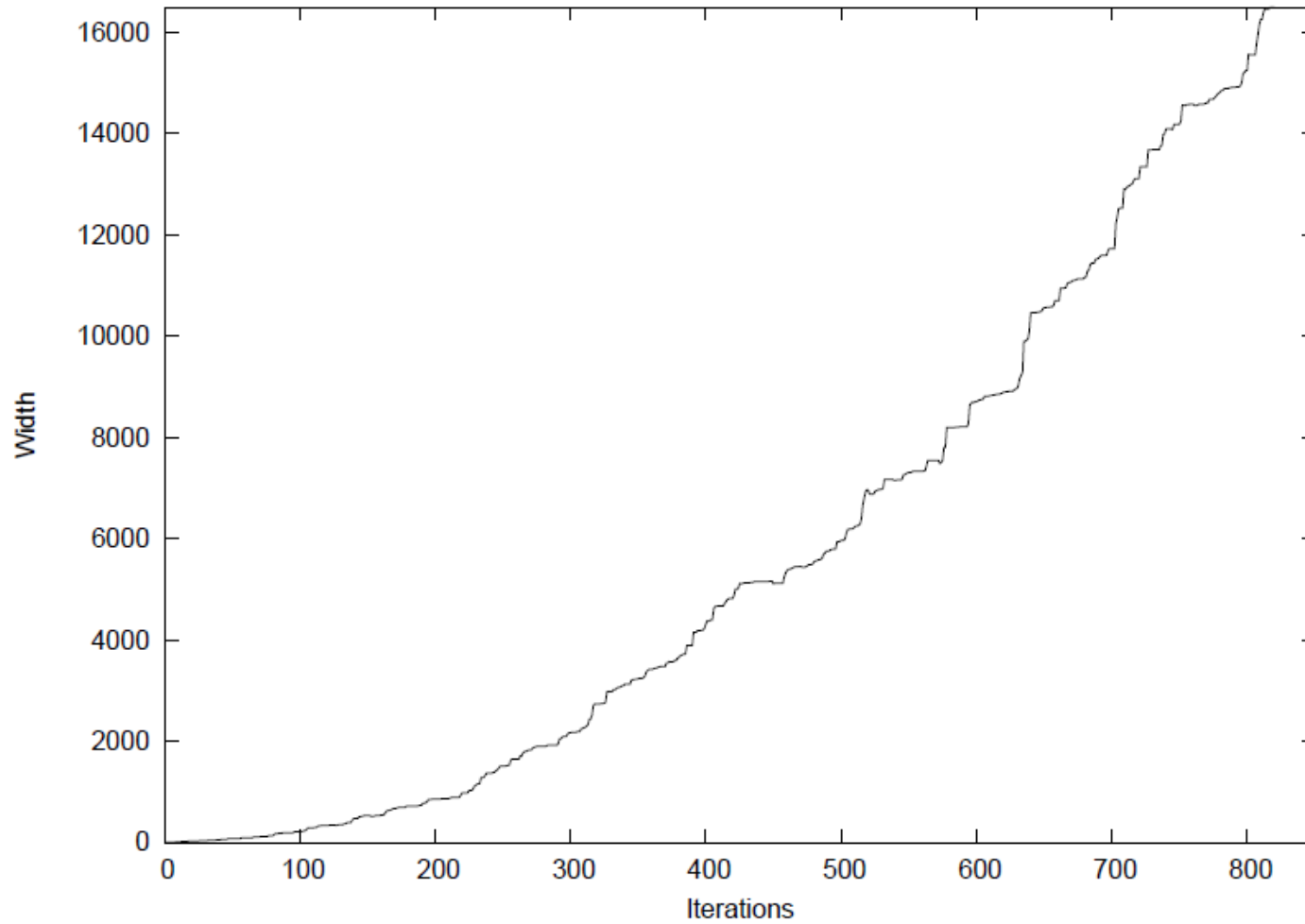
Growth of Separating Diagram for All but 3 Instances



Growth of Separating Diagram for 2 Harder Instances

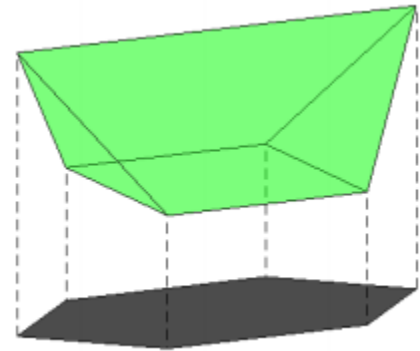


Growth of Separating Diagram for Hardest Instance



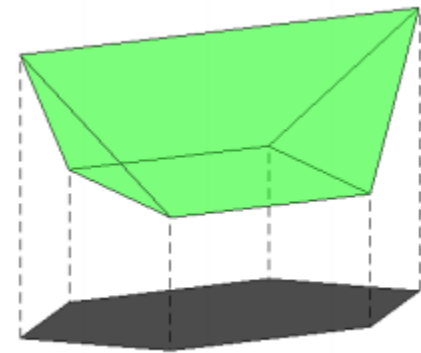
Logical Inference

- Connection between optimization and logic.
 - Both are **projection** problems.
 - Projection = extract information involving a subset of variables.



Logical Inference

- Connection between optimization and logic.
 - Both are **projection** problems.
 - Projection = extract information involving a subset of variables.
- Optimization...
 - **Project** feasible set onto a single variable representing the objective function.
- Inference...
 - **Project** knowledge base onto a subset of propositional variables.



Logical Inference

- Example:
 - Knowledge base consists of logical clauses.
 - Derive all implications involving x_1, x_2 .
 - This is a projection problem.

$$\begin{aligned} & x_1 \vee x_2 \\ & \neg x_1 \vee x_3 \\ & \neg x_1 \vee \neg x_2 \vee \neg x_3 \\ & x_1 \vee x_3 \vee x_4 \\ & x_2 \vee x_3 \vee \neg x_4 \end{aligned}$$

$$\begin{aligned} & x_1 \vee x_2 \\ & \neg x_1 \vee \neg x_2 \end{aligned}$$

Projection



Logical Inference

- Example:
 - Knowledge base consists of logical clauses.
 - Derive all implications involving x_1, x_2 .
 - This is a projection problem.
- Solved by logic-based Benders.
 - Clauses in the projection are Benders cuts
 - They are also **conflict clauses** containing x_1, x_2 from a SAT algorithm.

$$\begin{aligned} & x_1 \vee x_2 \\ & \neg x_1 \vee x_3 \\ & \neg x_1 \vee \neg x_2 \vee \neg x_3 \\ & x_1 \vee x_3 \vee x_4 \\ & x_2 \vee x_3 \vee \neg x_4 \end{aligned}$$

$$\begin{aligned} & x_1 \vee x_2 \\ & \neg x_1 \vee \neg x_2 \end{aligned}$$

Projection

Logical Inference

- A central problem today:
 - Associate each inference with its **probability**, **relevance**, or **confidence**.
 - For example, IBM's **Watson** (Jeopardy player).



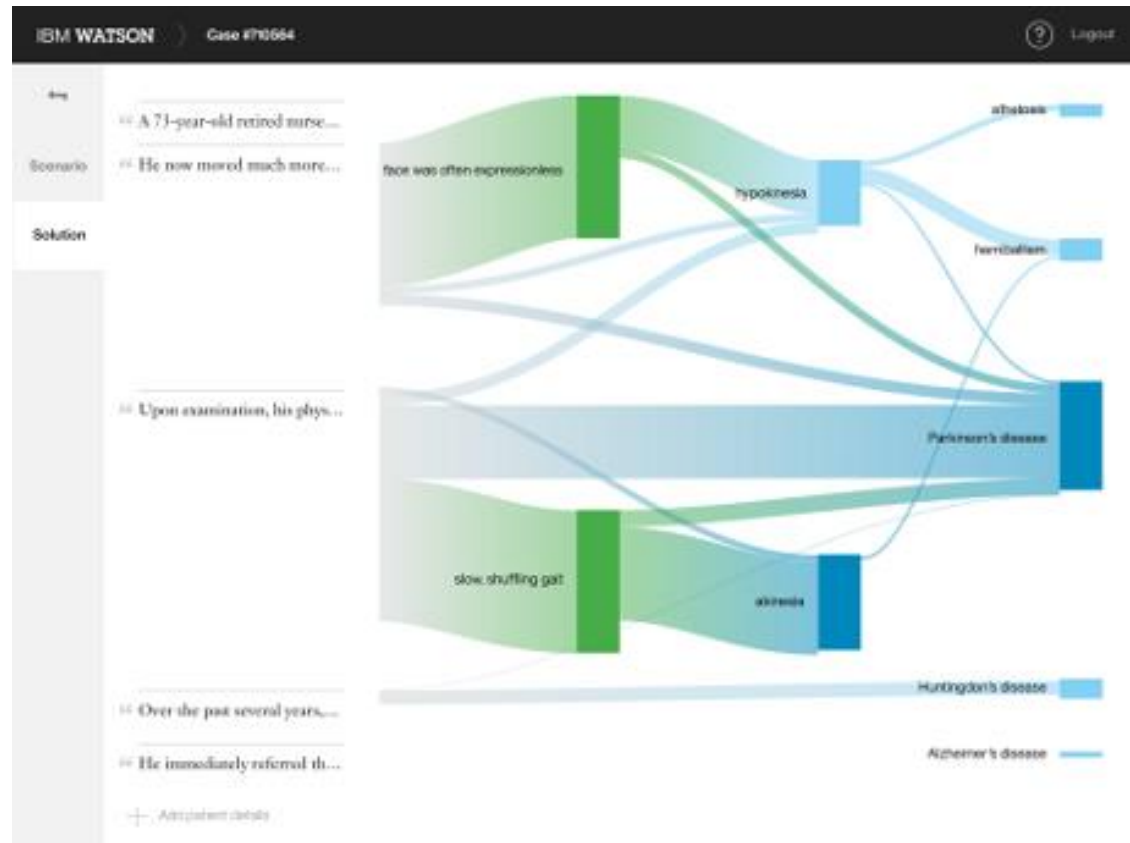
Logical Inference

Watson technology first applied to medicine (WatsonPaths).

Draws inferences from medical literature and clinical guidelines.

About 1 million articles listed per year in PubMed.

Probably 1.5-2 million overall.

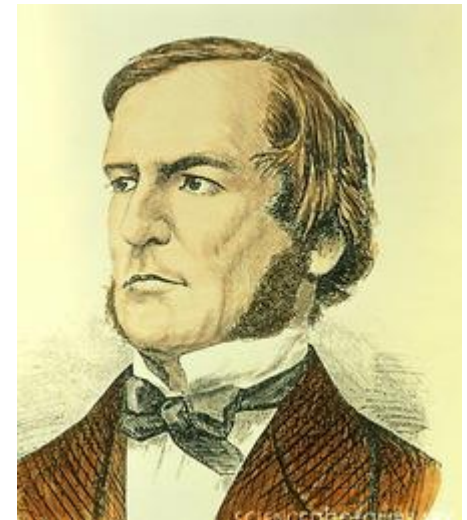


Logical Inference

- The problem was first posed for **probability**...

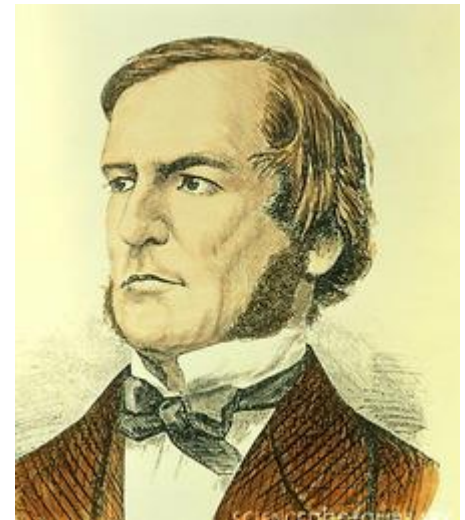
Logical Inference

- The problem was first posed for **probability**...
 - ...by George Boole.
 - He viewed **probability logic** as a key contribution.



Logical Inference

- The problem was first posed for **probability**...
 - ...by **George Boole**.
 - He viewed **probability logic** as his most important contribution.
 - Formulated inference problem as **linear programming**.
 - Can be solved by modern **column generation** methods.



Logical Inference

Example

Clause	Probability
--------	-------------

x_1	0.9
-------	-----

$\bar{x}_1 \vee x_2$	0.8
----------------------	-----

$\bar{x}_2 \vee x_3$	0.4
----------------------	-----

Deduce probability
range for x_3

Logical Inference

Example

Clause Probability

x_1 0.9

$\bar{x}_1 \vee x_2$ 0.8

$\bar{x}_2 \vee x_3$ 0.4

Deduce probability
range for x_3

Linear programming model

min/ max π_0

$$\begin{bmatrix} 01010101 \\ 00001111 \\ 11110011 \\ 11011101 \\ 11111111 \end{bmatrix} \begin{bmatrix} p_{000} \\ p_{001} \\ p_{010} \\ \vdots \\ p_{111} \end{bmatrix} = \begin{bmatrix} \pi_0 \\ 0.9 \\ 0.8 \\ 0.4 \\ 1 \end{bmatrix}$$

p_{000} = probability that $(x_1, x_2, x_3) = (0, 0, 0)$

Logical Inference

Example

Clause Probability

x_1 0.9

$\bar{x}_1 \vee x_2$ 0.8

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Deduce probability
range for x_3

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p_{000} = probability that $(x_1, x_2, x_3) = (0, 0, 0)$

Solution: $\pi_0 \in [0.1, 0.4]$

Logical Inference

- Next steps
 - Apply **large-scale optimization** methods to logical inference.
 - They are substantially **underutilized** for this purpose.
 - In particular:
 - Use **logic-based Benders** for propositional logic, etc.
 - Use **column generation** for probability logic.
 - Use **linear programming** for belief logics, relevance, and variations of Dempster-Shafer theory.
 - Use **nonlinear programming** for Bayesian networks.
 - Use **decision diagrams** for queries and what-if analysis.

Andersen, JH (1992,1994,1996)

Chandru, JH (1999)